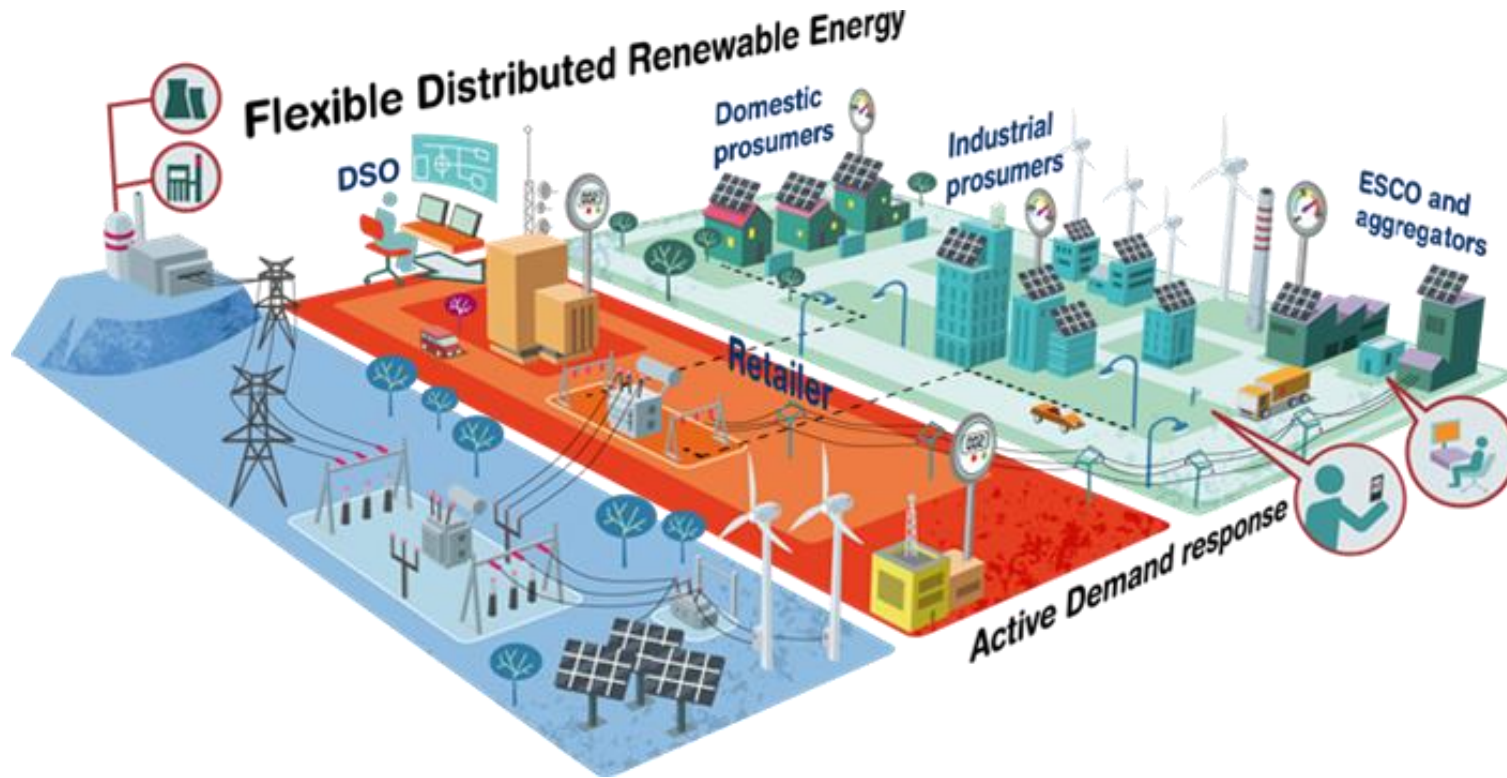


Multi-objective model predictive control for smart and energy flexible buildings

Krzysztof Arendt
Postdoctoral Researcher

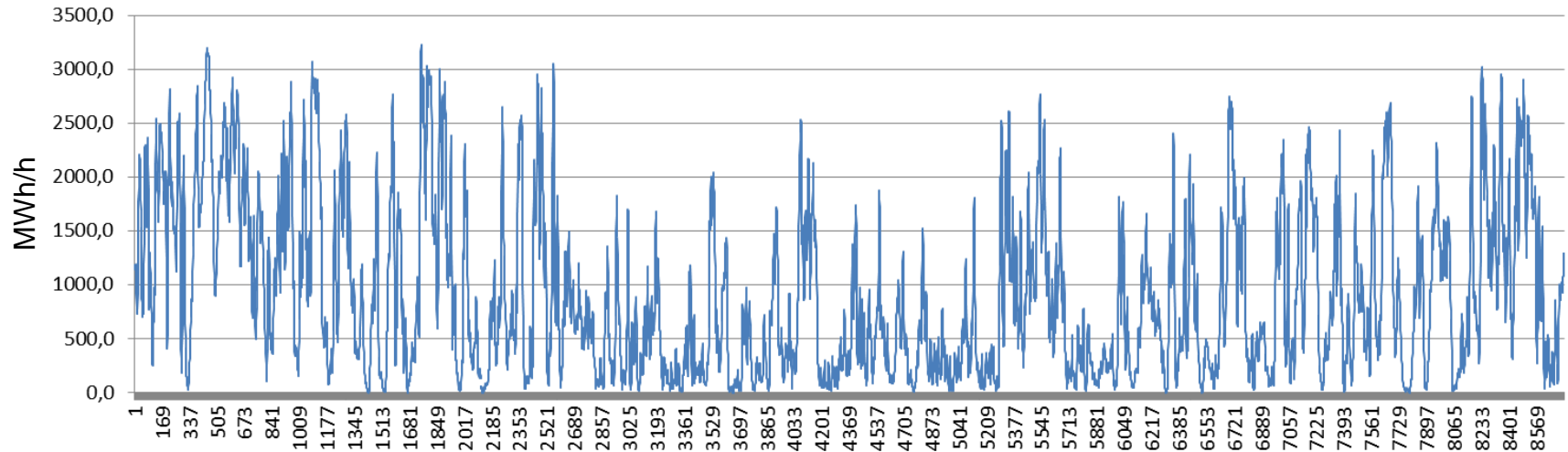
Center for Energy Informatics
SDU

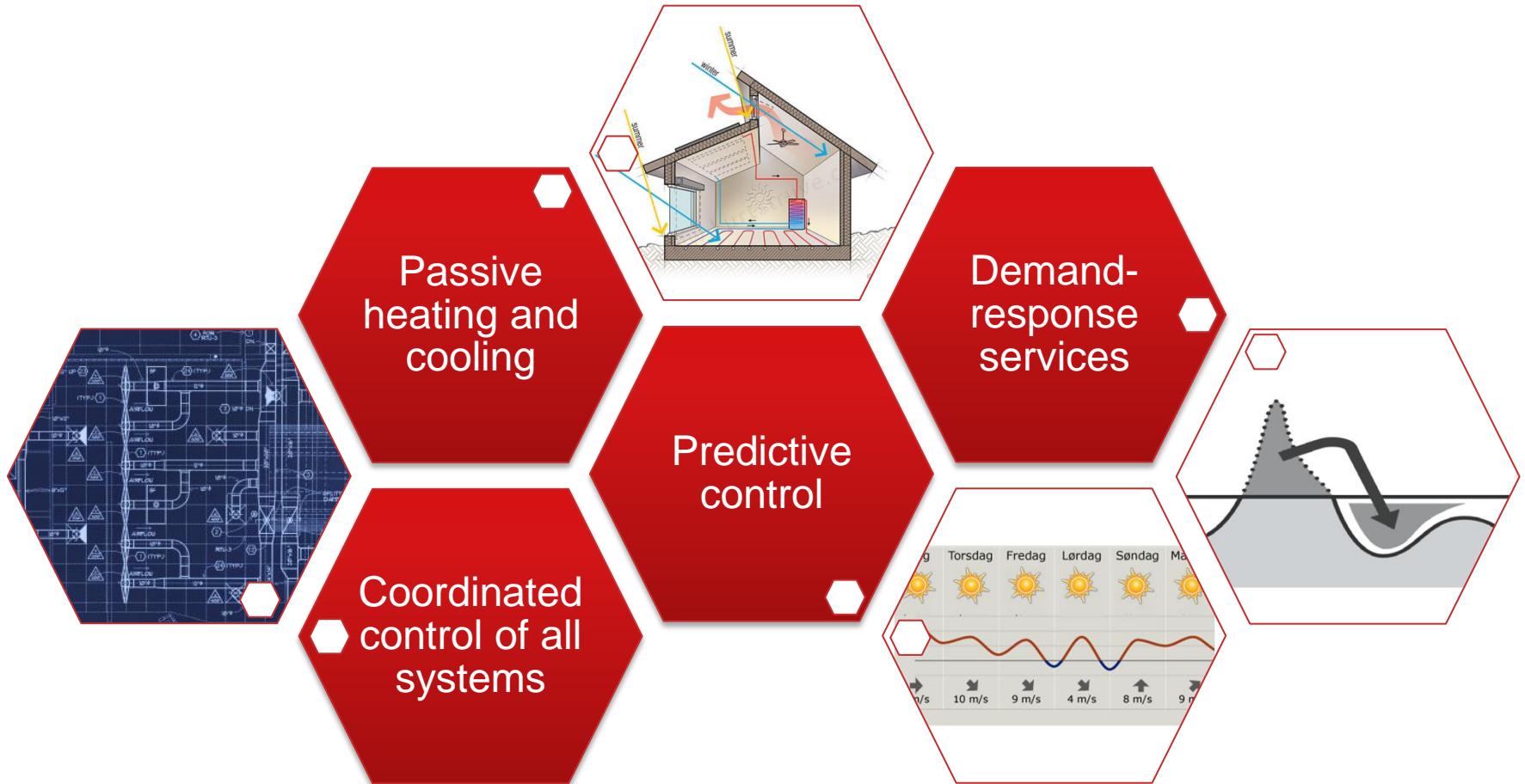
October 5, 2017
Climate Neutrality Conference
Sønderborg



The Center's mission is to participate in the green transition of the energy system by focusing on Innovative ICT-based solutions for energy-efficiency improvements in buildings and industrial processes and intelligent integration of the energy flexibility, at the consumer side, with the fluctuating production from renewable energy sources.

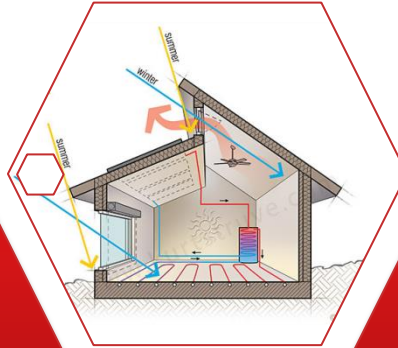
Renewable energy challenge





Smart buildings

Take the advantage of
building dynamics,
**NOT WORK
AGAINST IT**

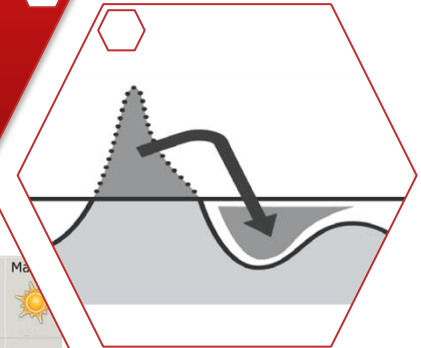
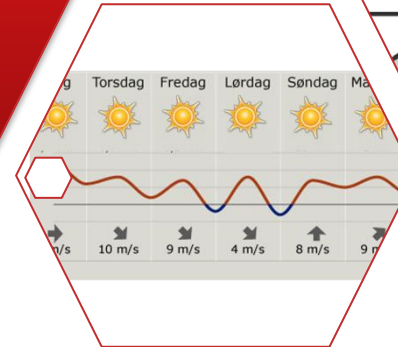


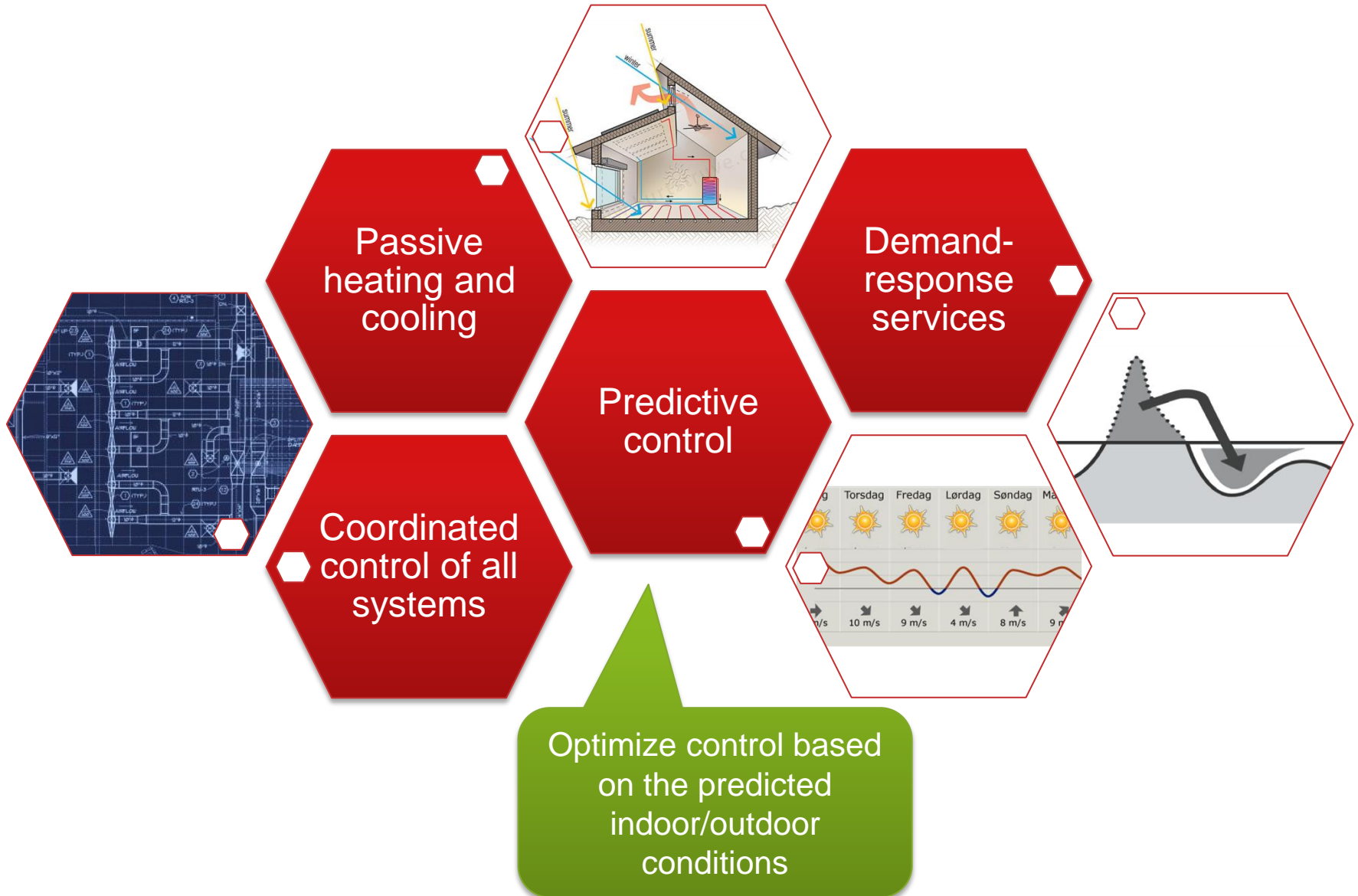
Passive
heating and
cooling

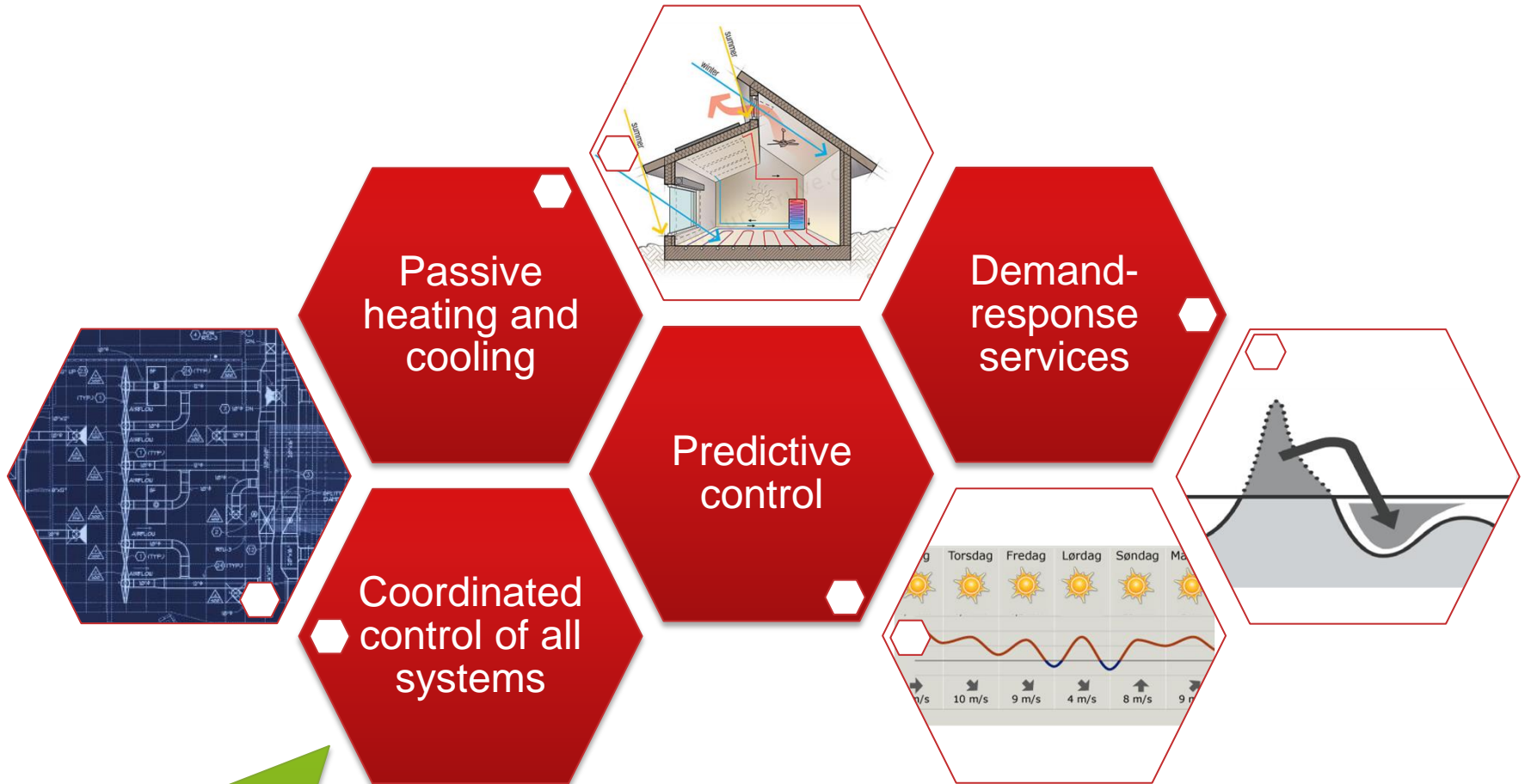
Demand-
response
services

Predictive
control

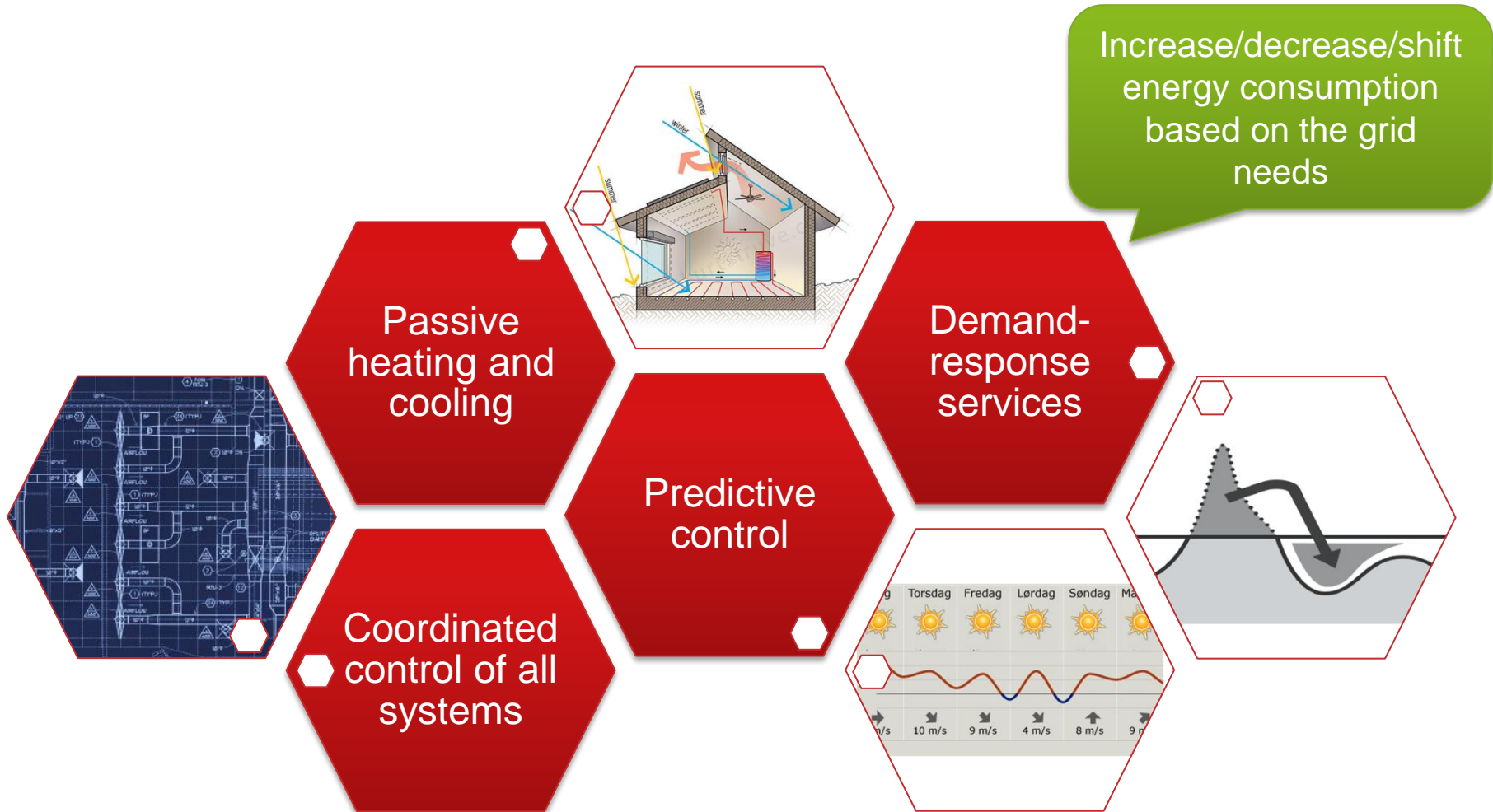
Coordinated
control of all
systems

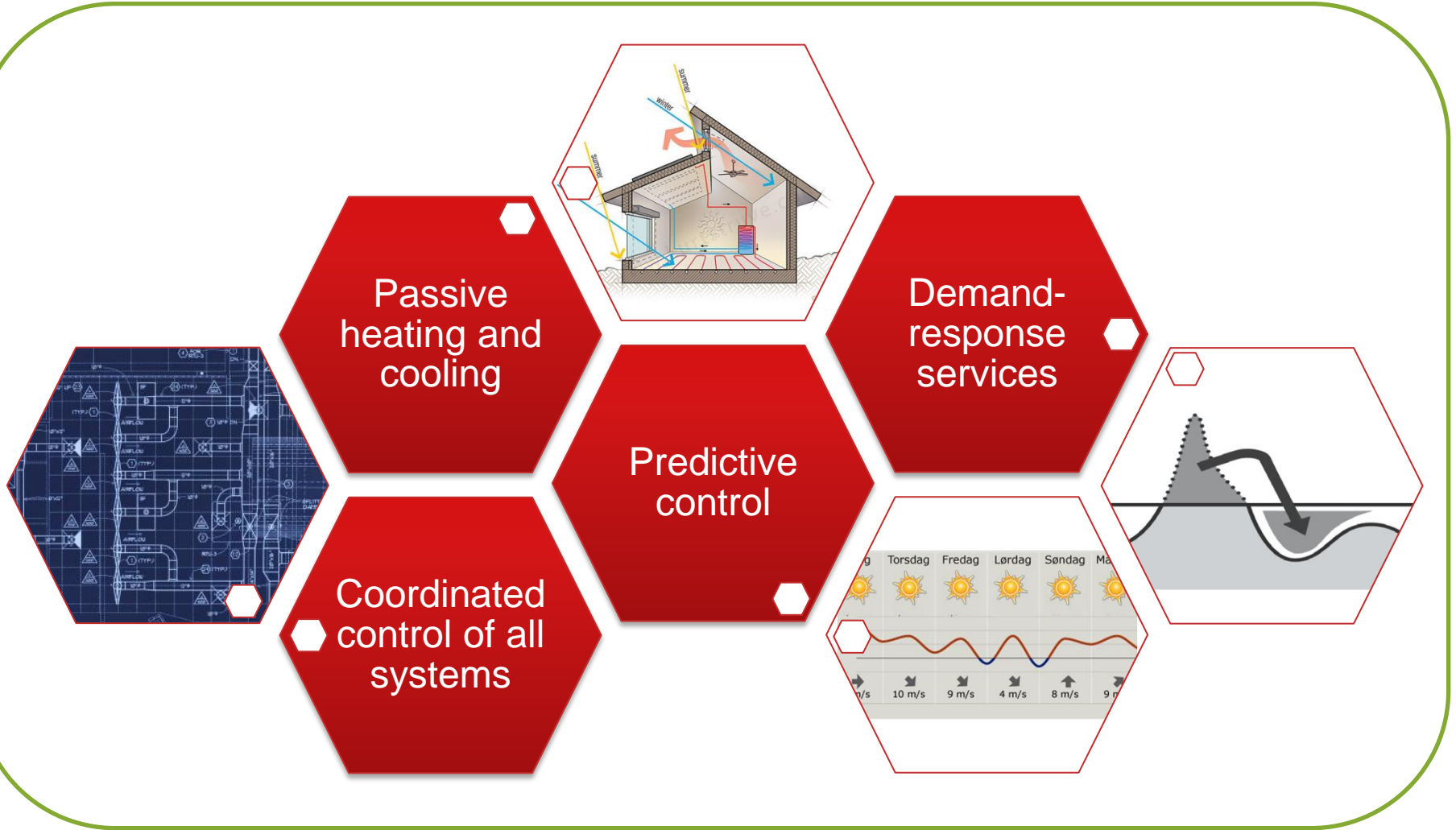






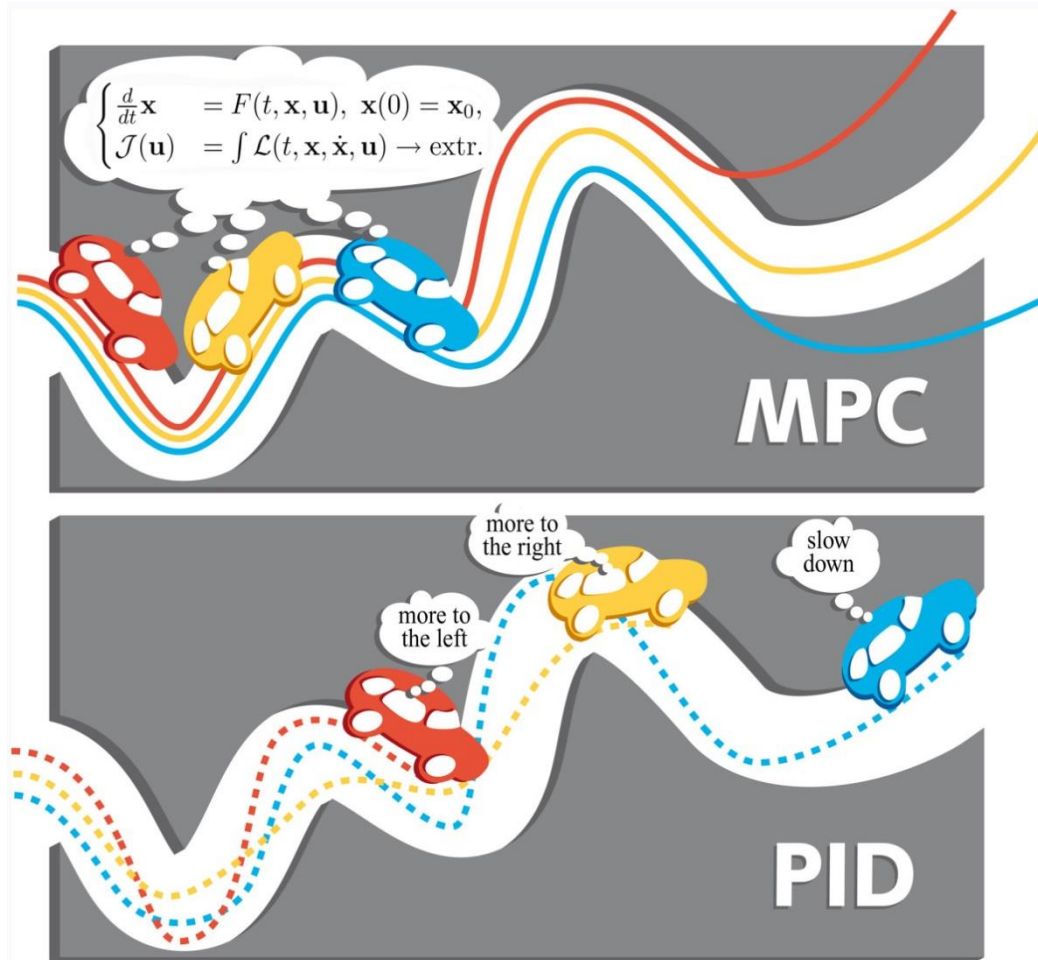
Systems need to talk to one another, e.g. to avoid simultaneous heating and cooling





HOLISTIC APPROACH NEEDED!

Standard vs. predictive control

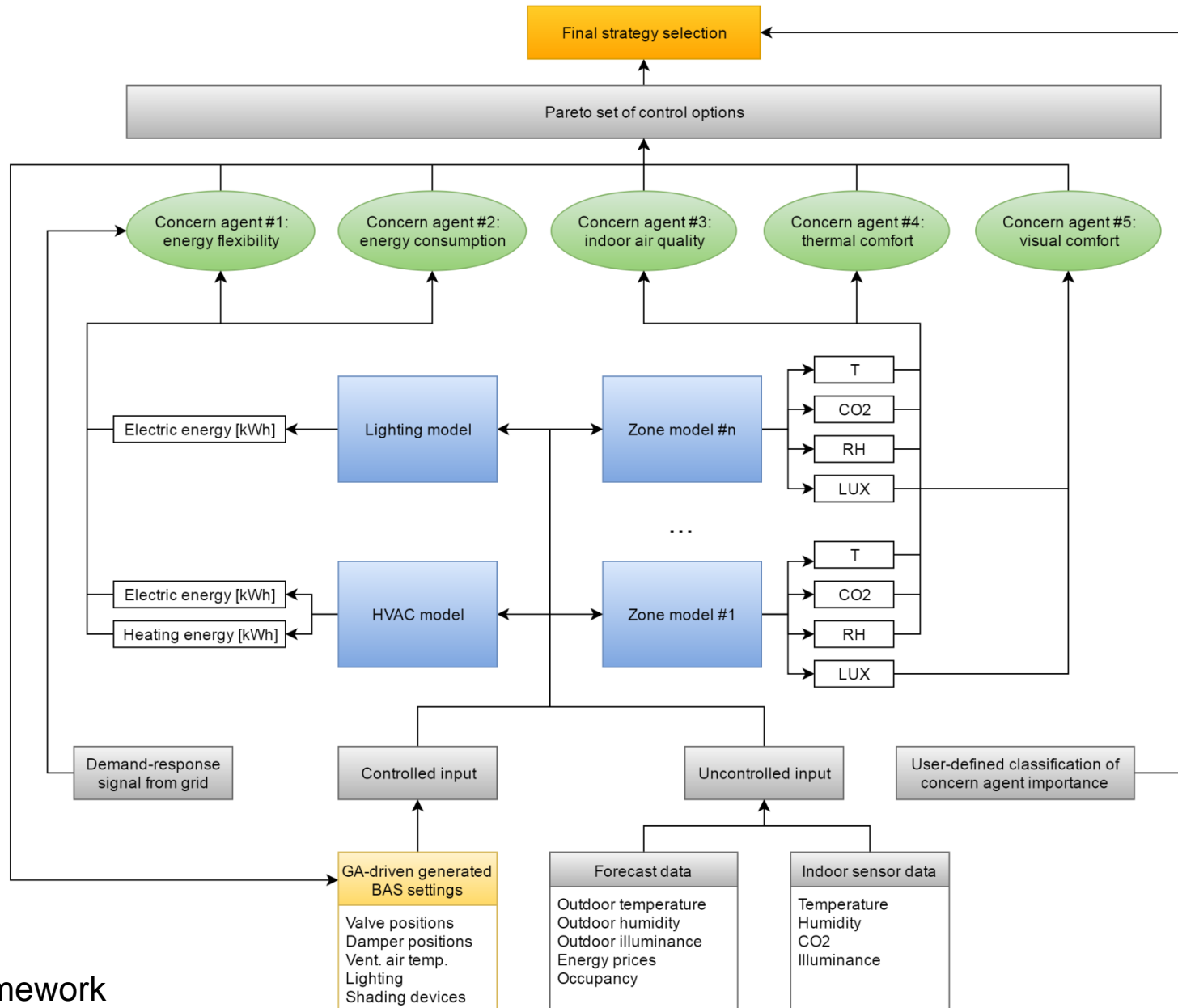


Model Predictive Control (MPC) control strategy adapting to the predicted future conditions

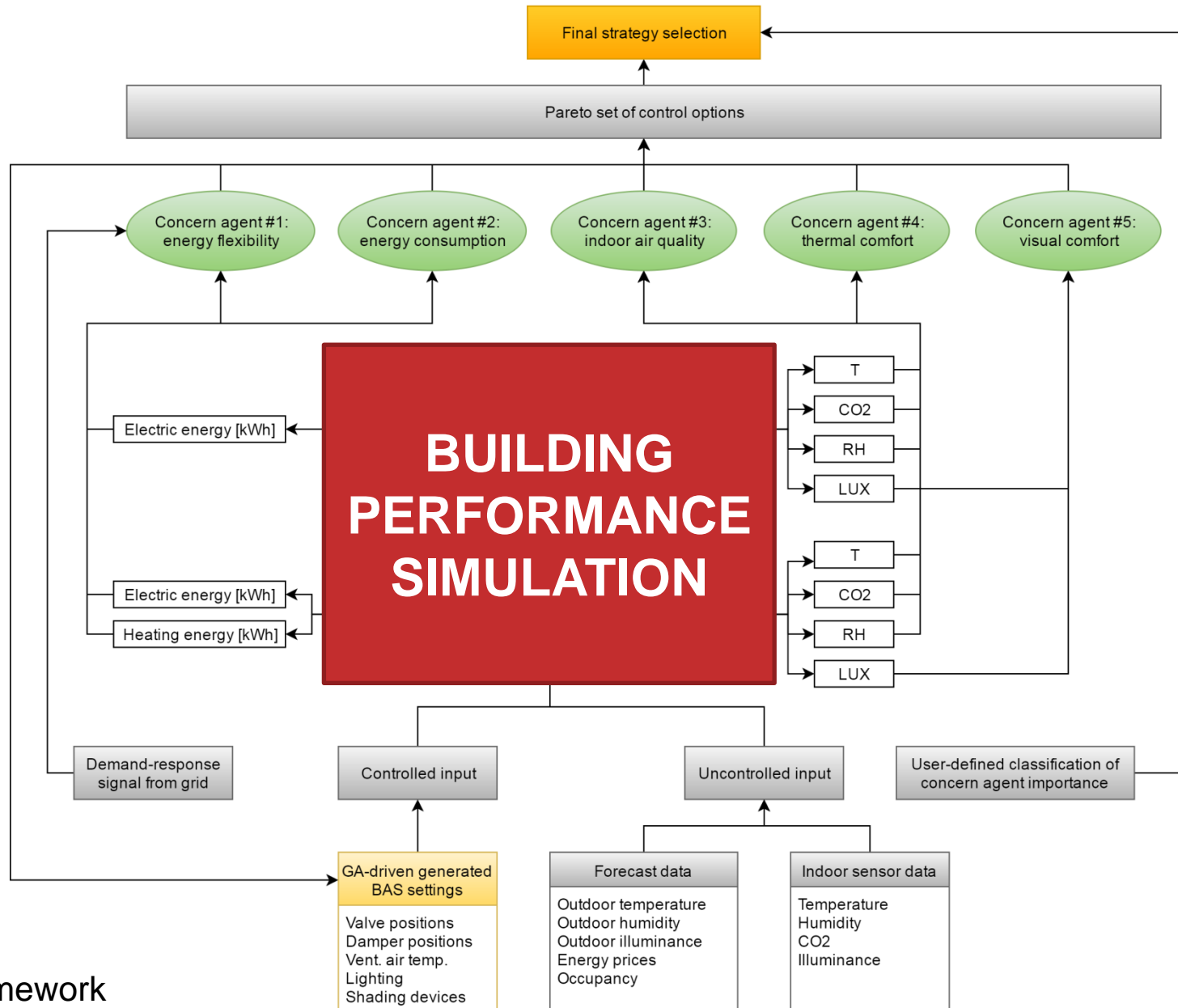
Traditional control strategy reacting to unexpected conditions

Image source: M. Hoekstra, M Vogelzang, E. Verbitsky, M.W.N. Nijtsen, Health technology assessment review: Computerized glucose regulation in the intensive care unit – how to create artificial control, *Critical Care* 2009 (13): 223.

Implementation of smart control solutions in OU44

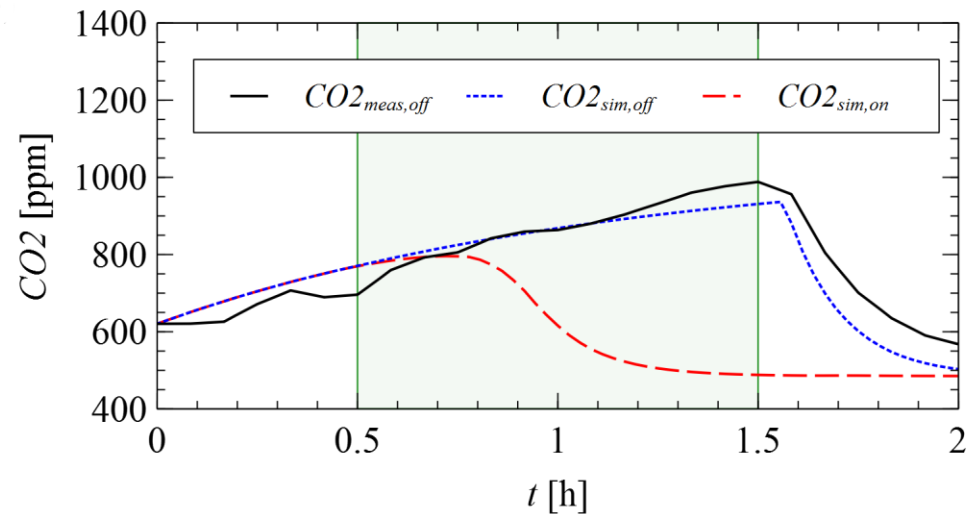


Implementation of smart control solutions in OU44



Capabilities:

- Prediction of future indoor conditions
- Possibility to compare the effect of different control strategies beforehand (see figure)



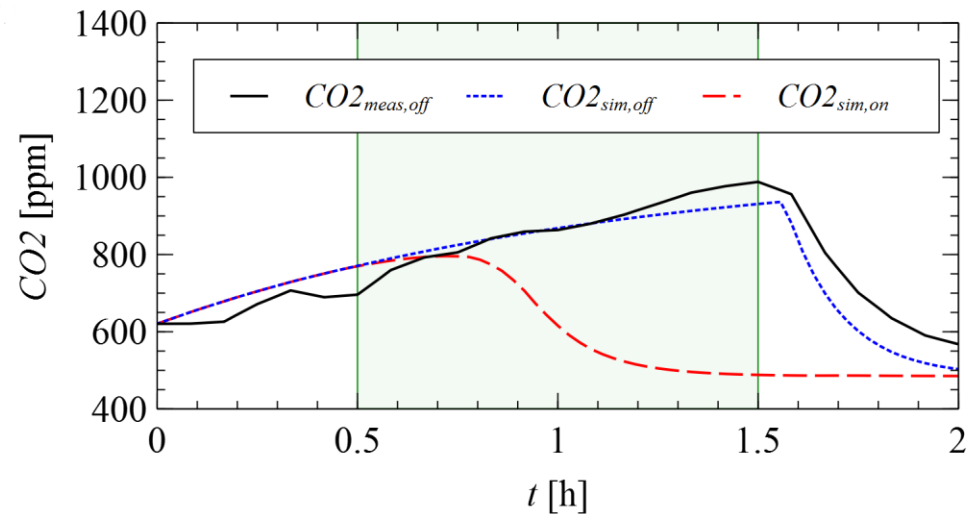
CO2 measured (ventilation OFF)
CO2 simulation (ventilation OFF)
CO2 simulation (ventilation ON)

Difficulties:

- Limited model portability
(numerical model is tailored for a specific building)
- Calibration of model parameters is difficult

Capabilities:

- Prediction of future indoor conditions
- Possibility to compare the effect of different control strategies beforehand (see figure)



CO2 measured (ventilation OFF)
CO2 simulation (ventilation OFF)
CO2 simulation (ventilation ON)

Difficulties:

- Limited model portability (numerical model is tailored for a specific building)
- Calibration of model parameters is difficult

Can we get automatic model generation and calibration?

Zone model for indoor environment prediction

Inputs:

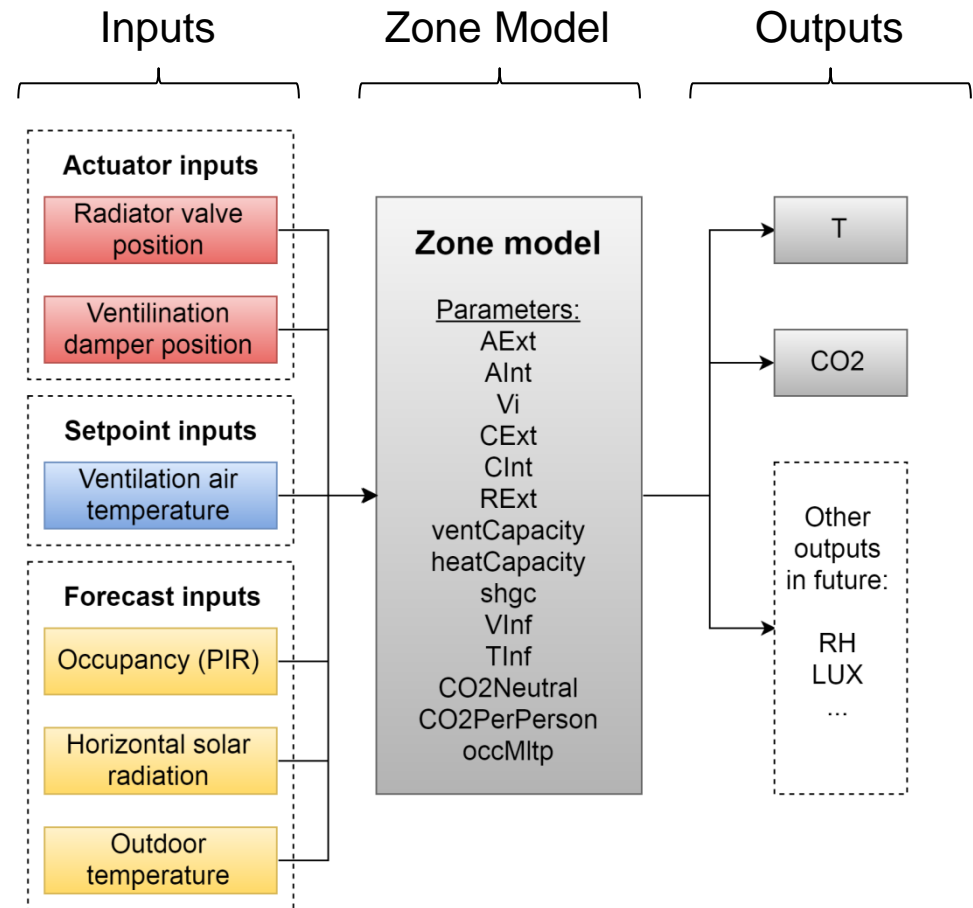
- Actuator positions
- Setpoints
- Forecast data

Model parameters:

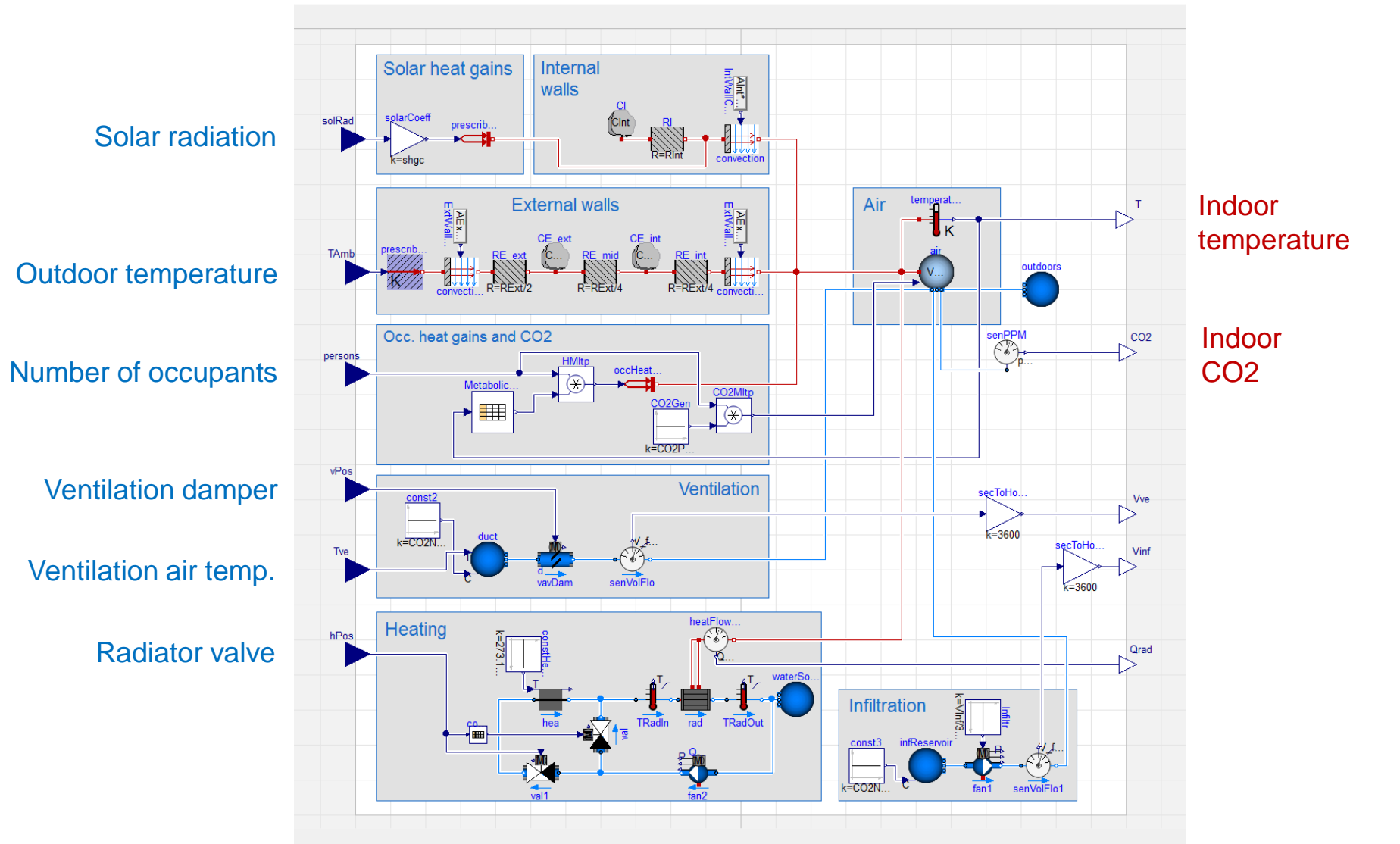
- Geometrical parameters
- Material parameters
- HVAC system capacity
- Typical occupancy behavior

Outputs:

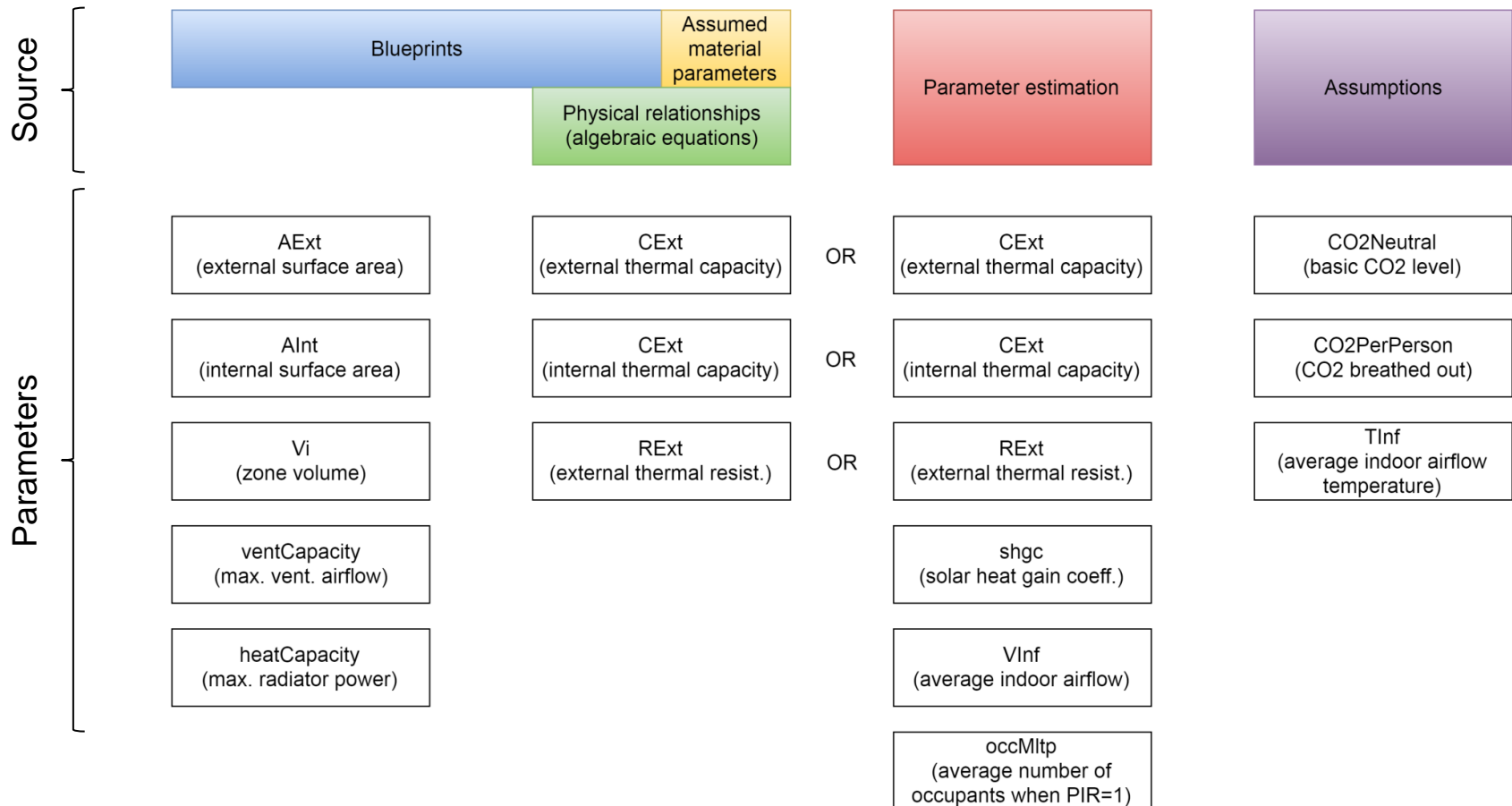
- Indoor temperature
- Indoor CO2



Zone model: implementation



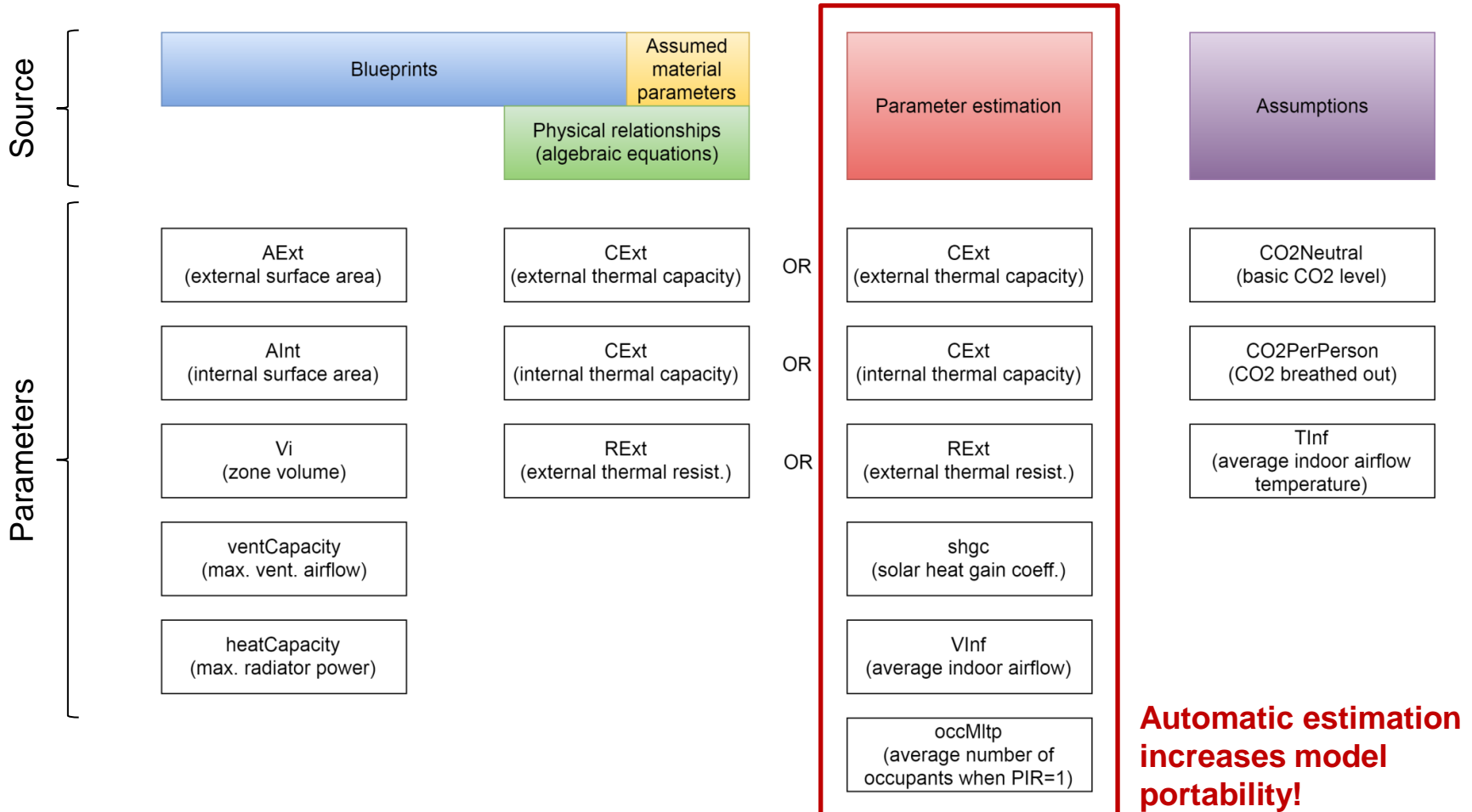
Parameter sources



Model parameters are:

(1) read from blueprints/BIM, (2) calculated from blueprints/BIM, (3) estimated, (4) assumed

Parameter sources

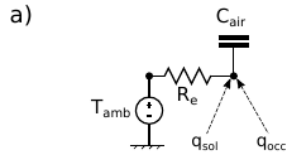


Model parameters are:

(1) read from blueprints/BIM, (2) calculated from blueprints/BIM, (3) estimated, (4) assumed

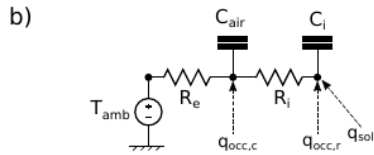
Low-order zone thermal models

R1C1



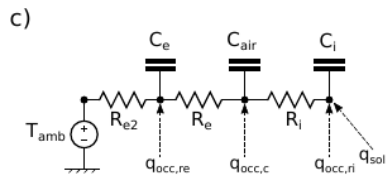
Convex

R2C2



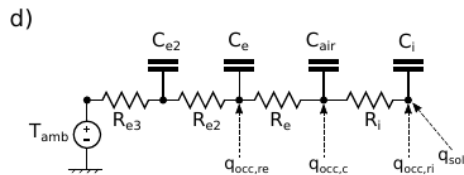
Convex / non-convex

R3C3



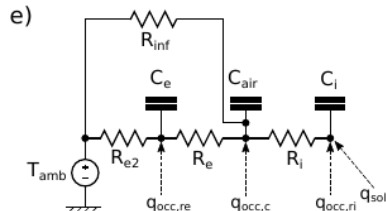
Non-convex

R4C4



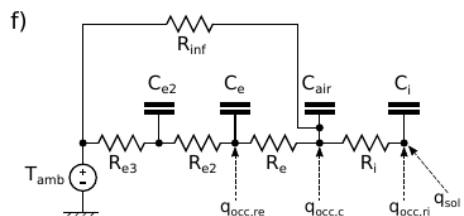
Non-convex

R4C3



Non-convex

R5C4



Non-convex

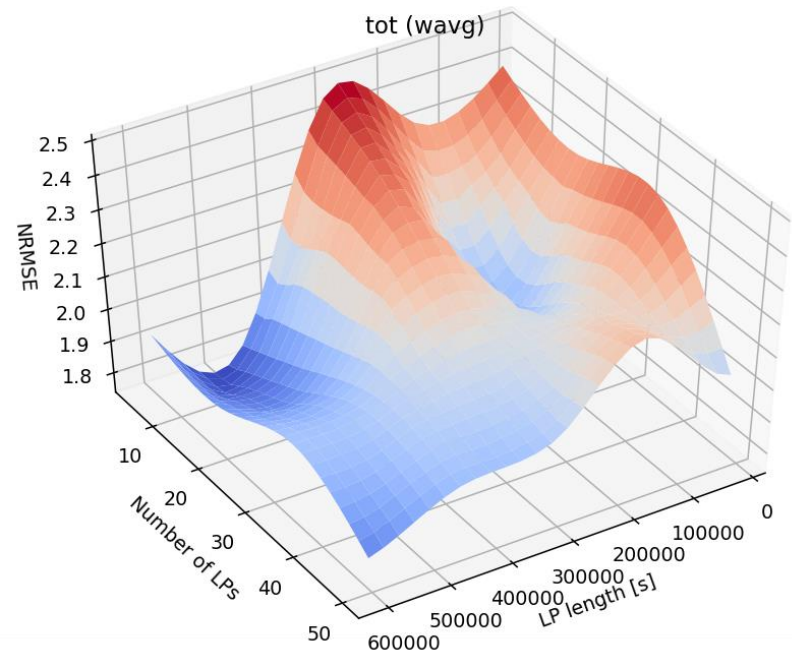


Fig: Non-convex function: model error depending on number and length of learning periods

Low-order model results: all cases

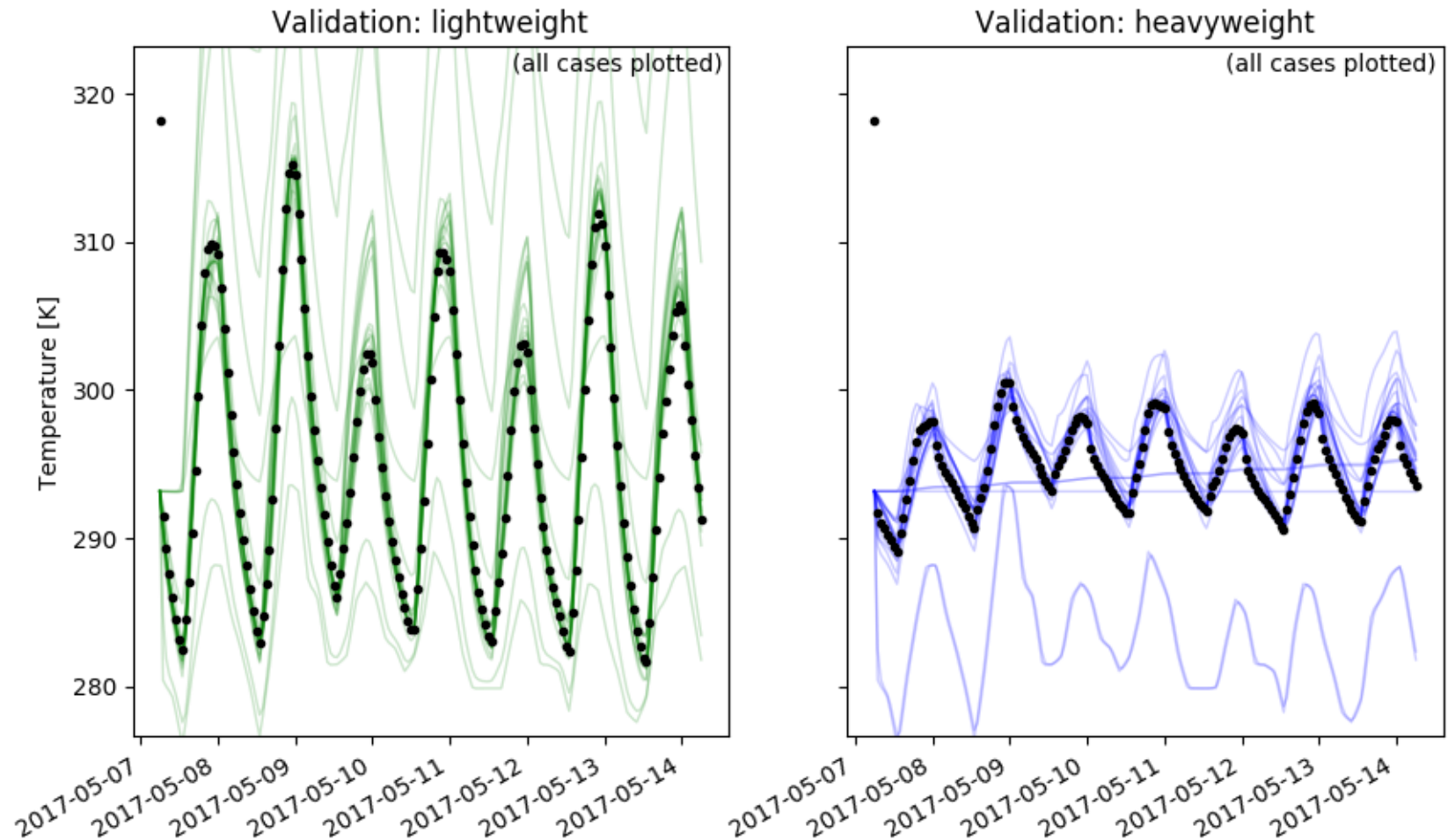


Fig: Actual temperature (dotted) vs. low-order model results (green/blue) for all estimated parameters – highlights the need for robust parameter estimation method

modest^{py}

<https://github.com/sdu-cfei/modest-py>

- ✓ Parameter estimation
- ✓ Optimization
- ✓ Genetic algorithm (global search)
- ✓ Hooke-Jeeves (local search)
- ✓ Open source (BSD)
- ✓ Windows & Linux
- ✓ Non-convex optimization
- ✓ Non-linear models
- ✓ Non-differentiable models
- ✓ FMI-compliant



ModestPy: step 1 – genetic algorithm

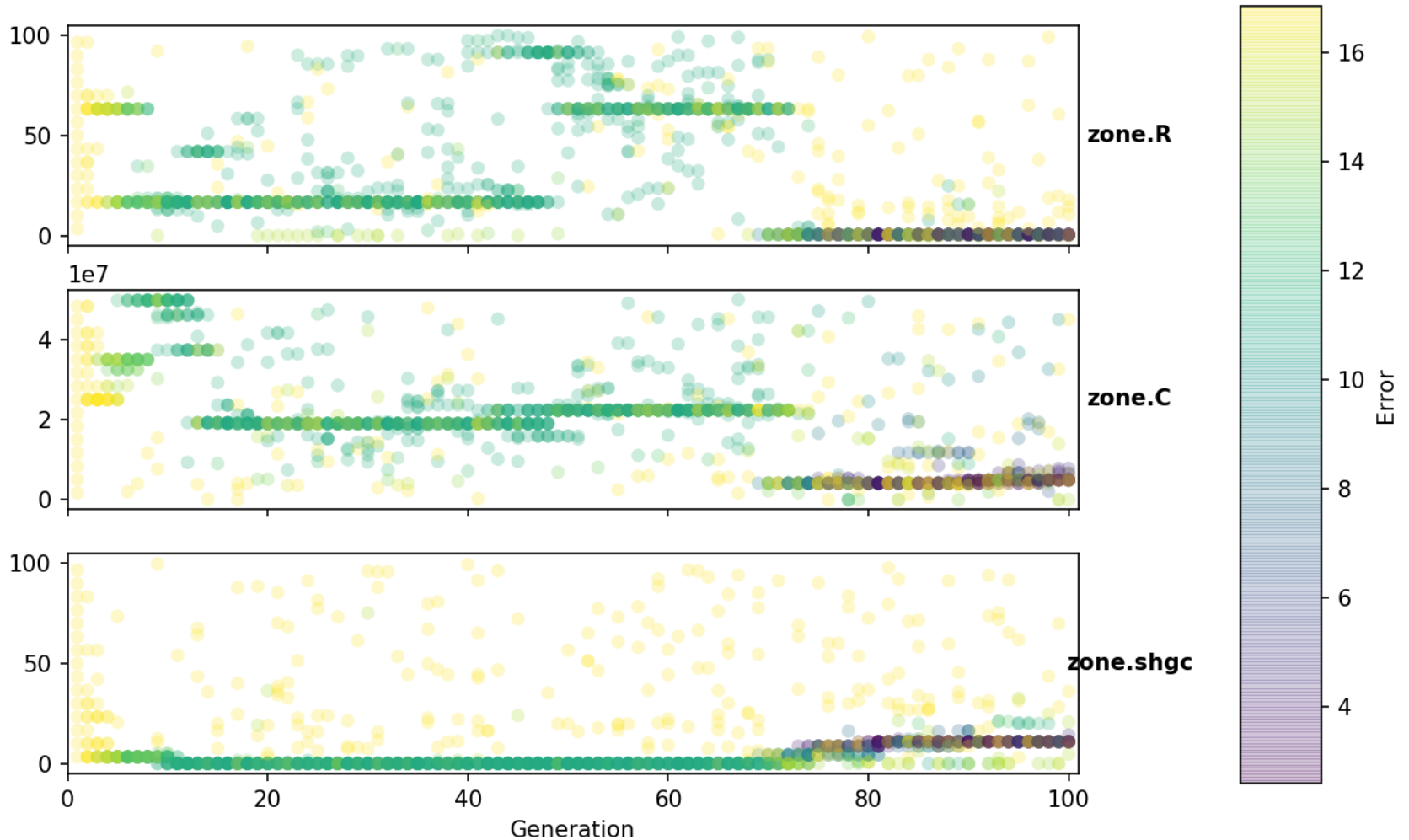


Fig: Visual representation of the genetic algorithm evolution

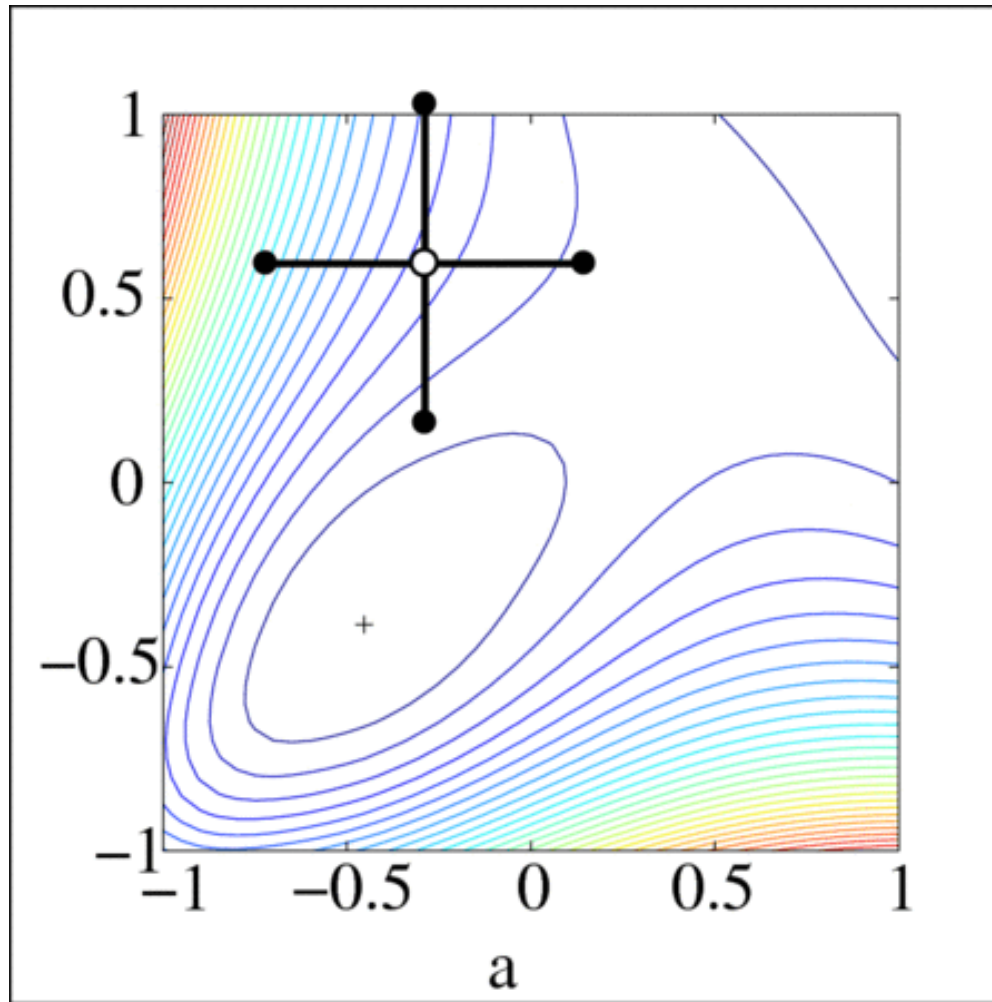


Fig: Hooke-Jeeves (pattern search) algorithm

ModestPy: step 2 – Hooke-Jeeves

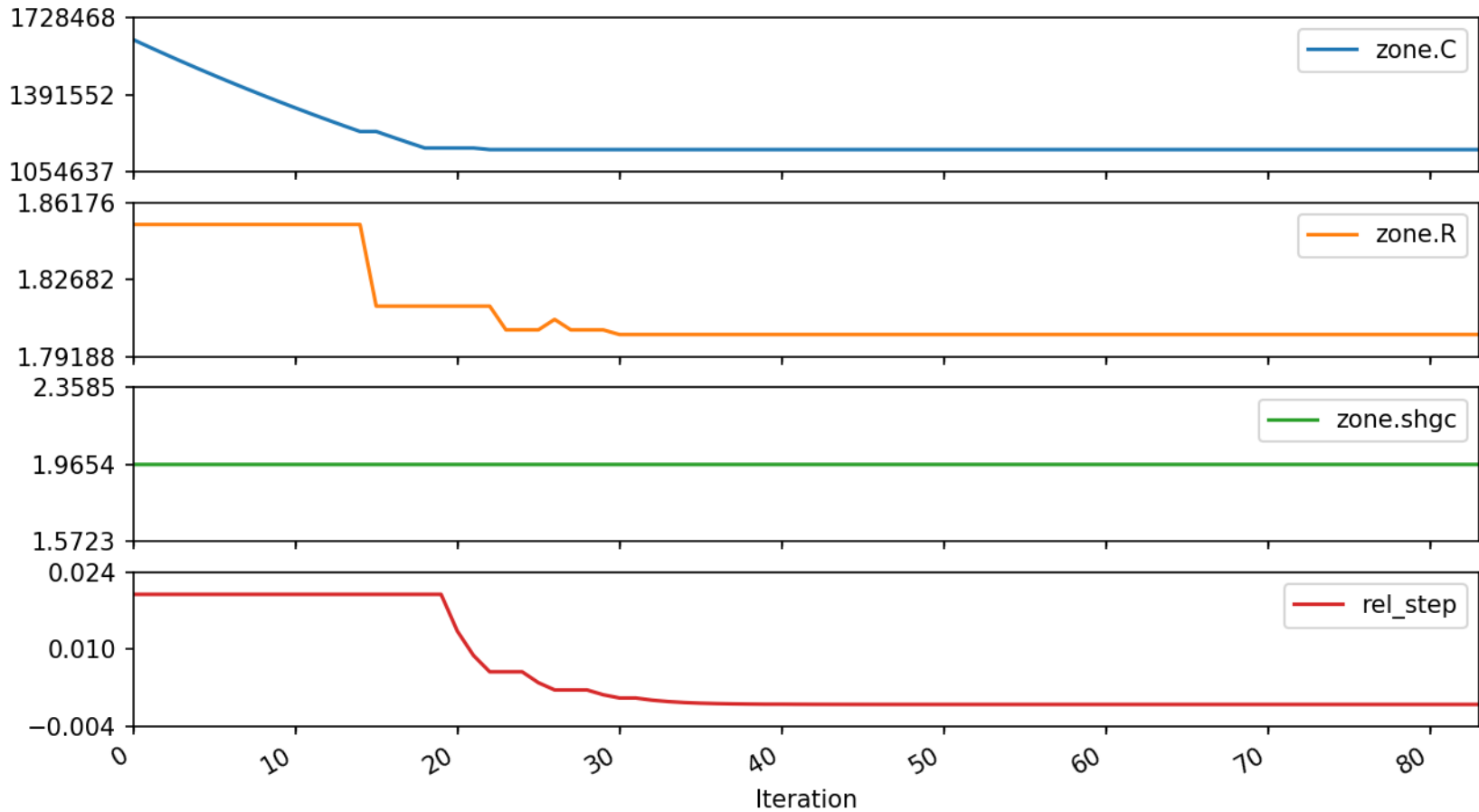


Fig: Hooke-Jeeves (pattern search) results

Convex example: R1C1

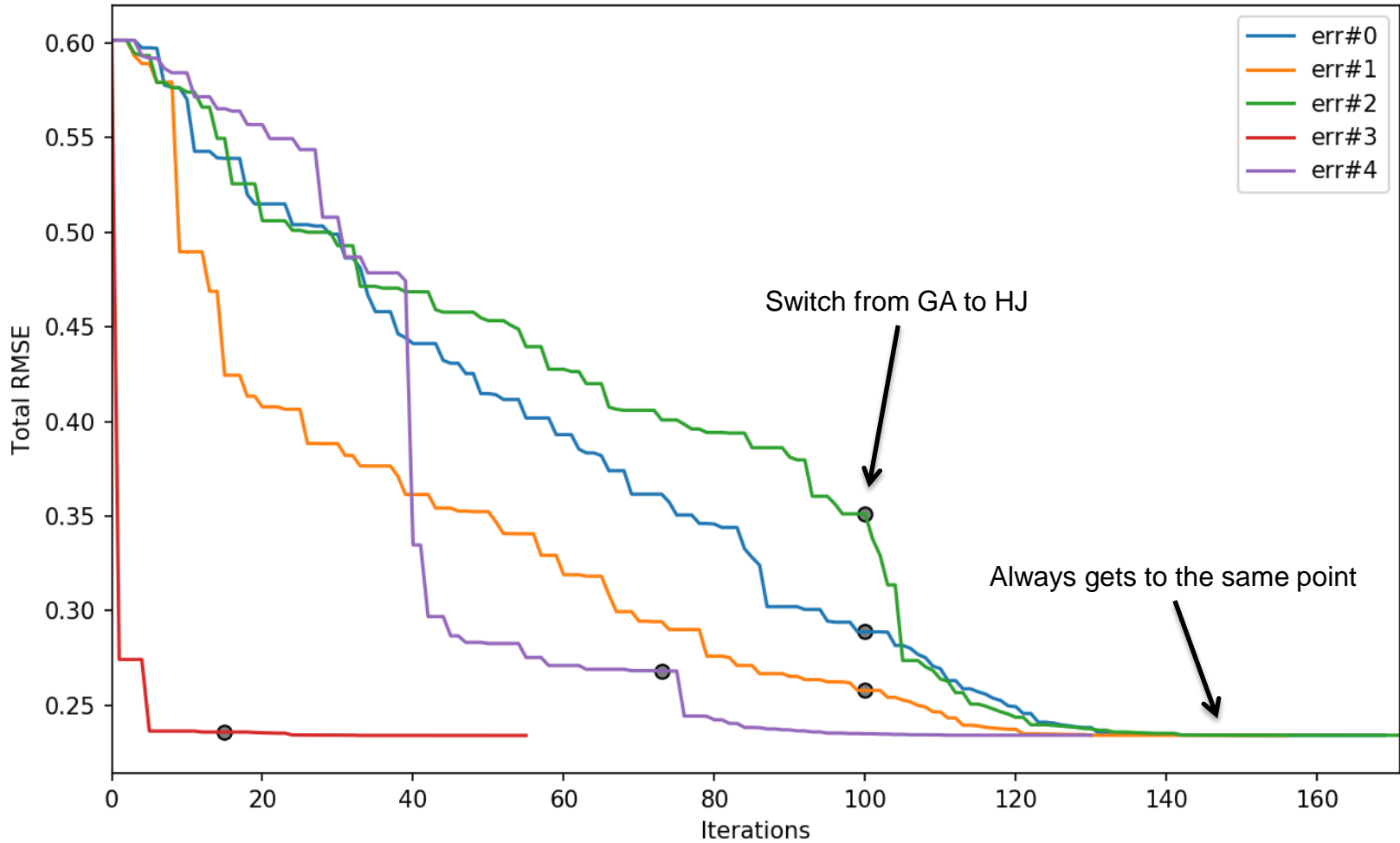


Fig: RMSE in 5 estimation runs on convex problem

Non-convex example: R5C4

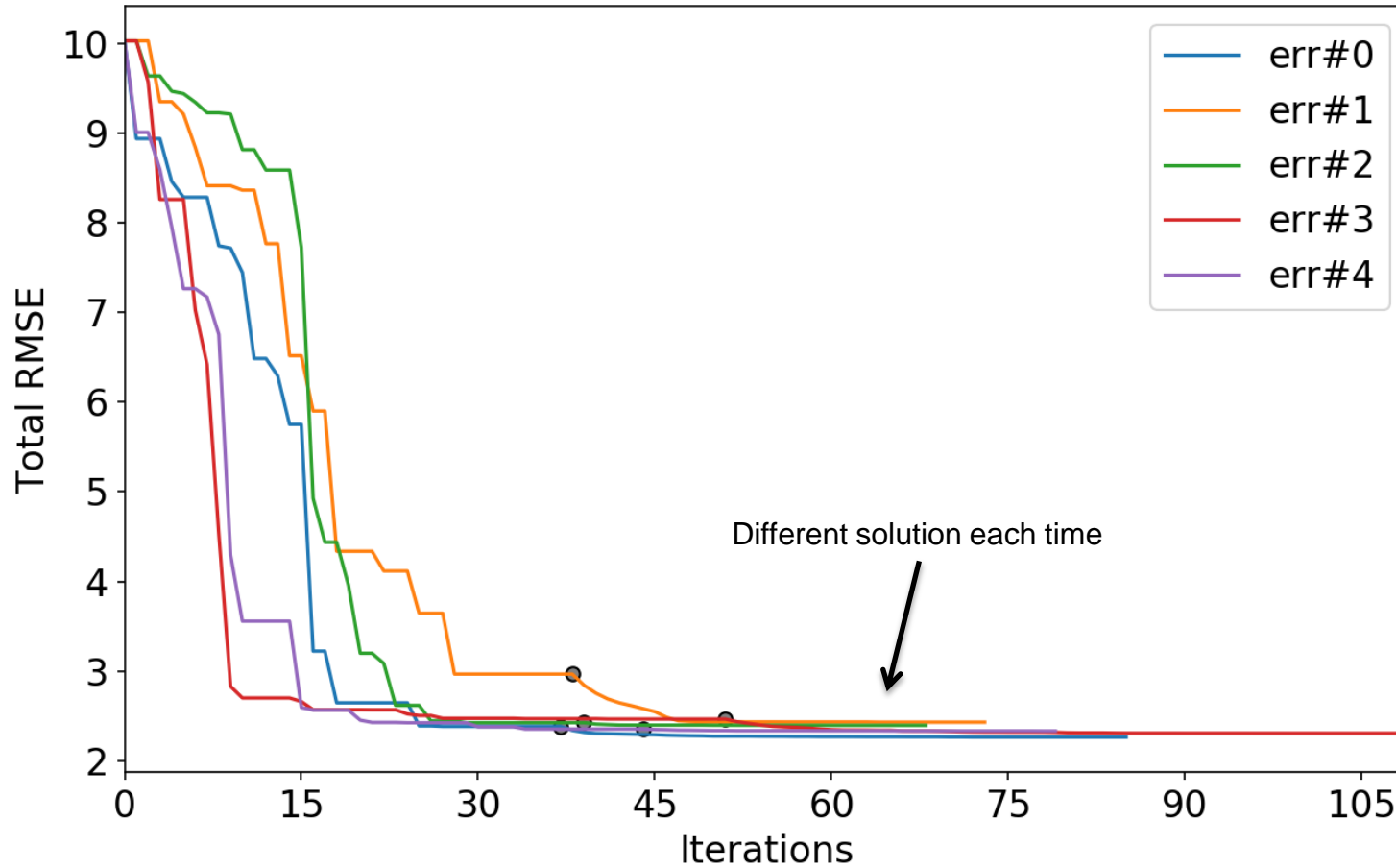


Fig: RMSE in 5 estimation runs on non-convex problem

Model accuracy vs. building type

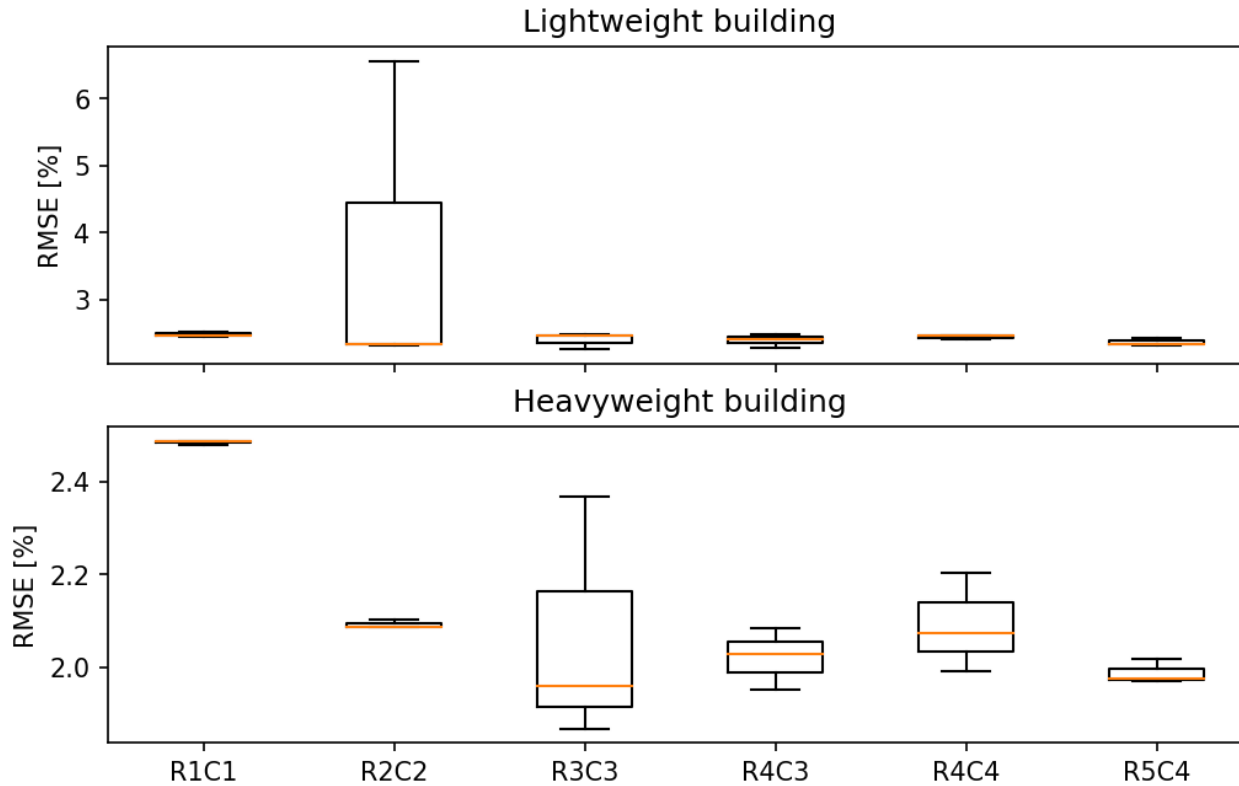
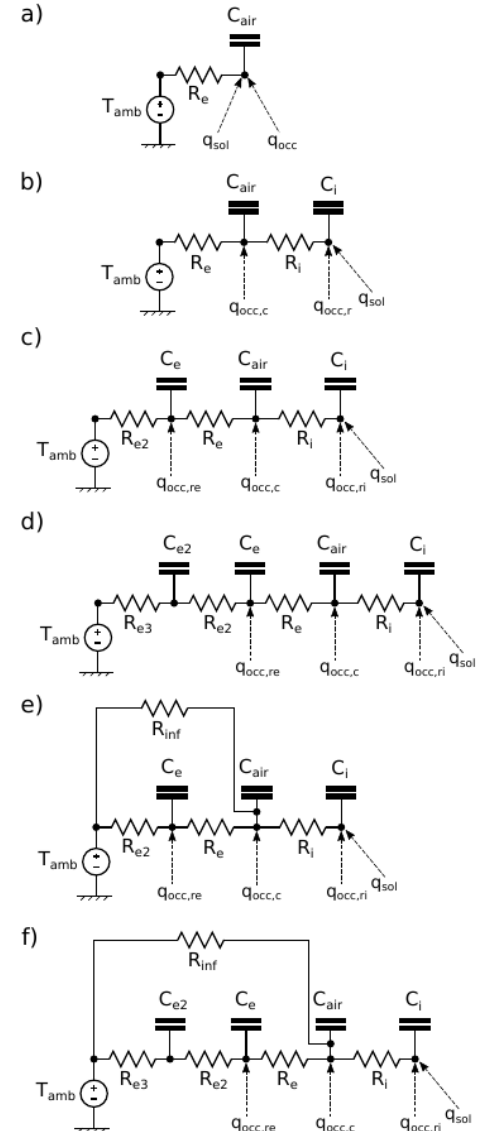
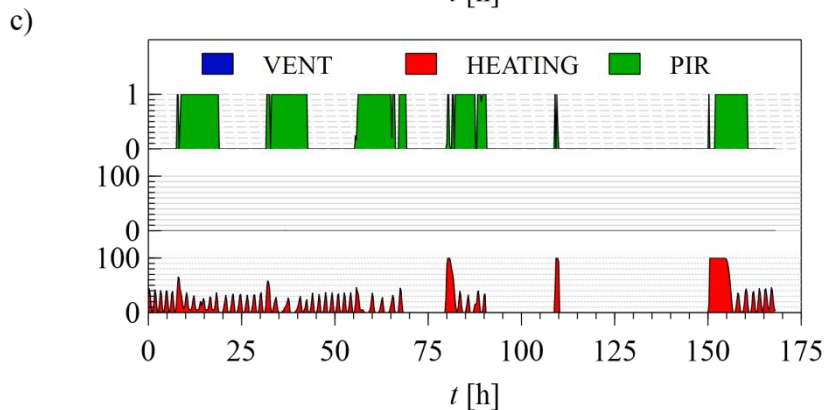
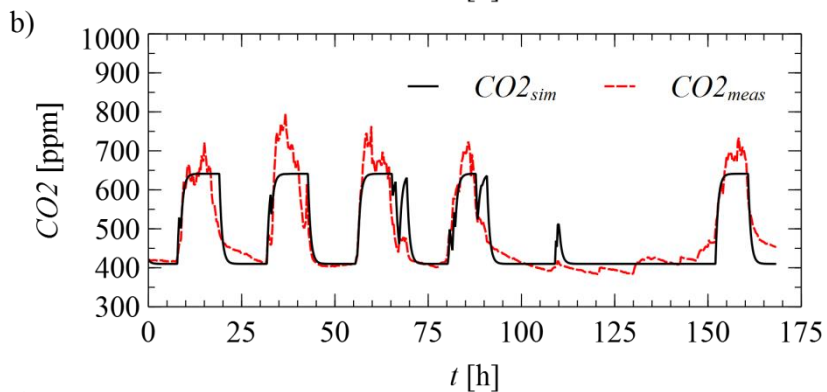
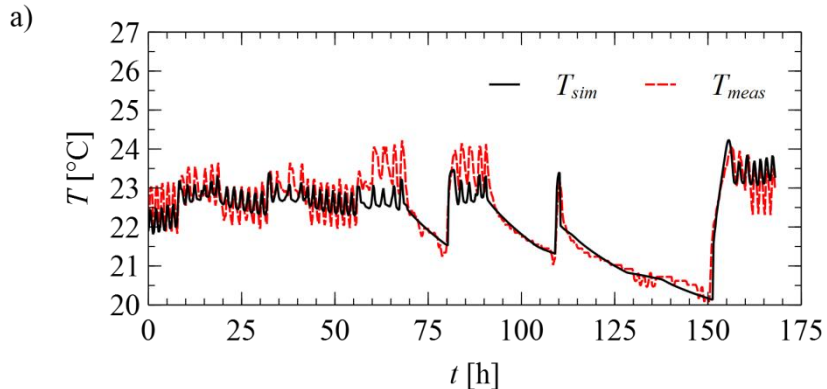


Fig: RMSE of 5 low order models (on the right) depending on the building type



Calibrated model results: GTH, room 1H1



(01-03-2016 00:00:00 – 08-03-2016 00:00:00)

Figures:

- a) Temperature: simulation vs. measured
- b) CO₂: simulation vs. measured
- c) Ventilation, heating, PIR inputs

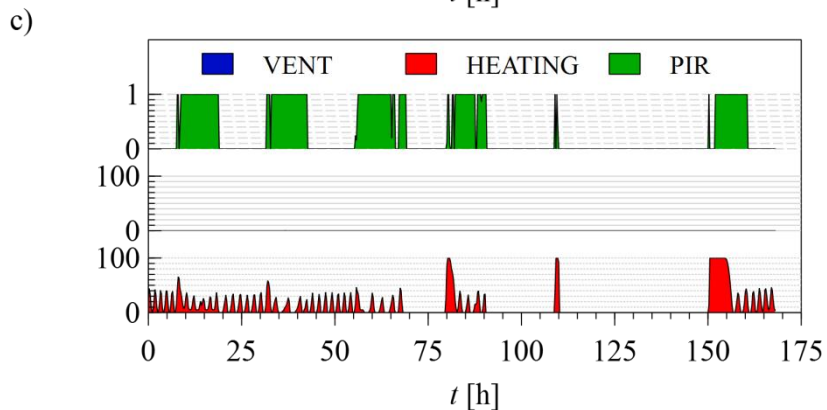
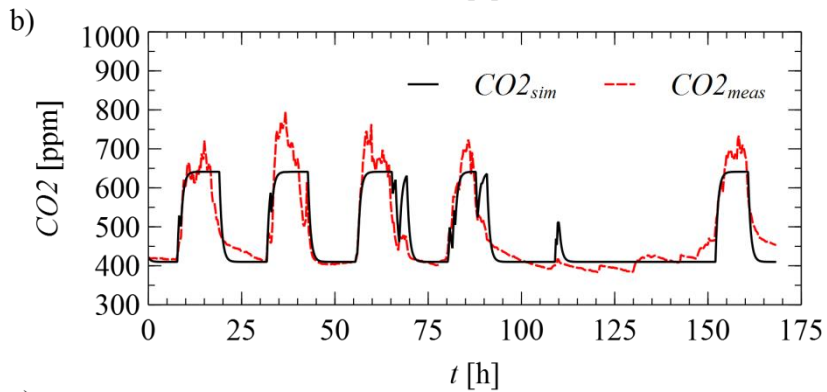
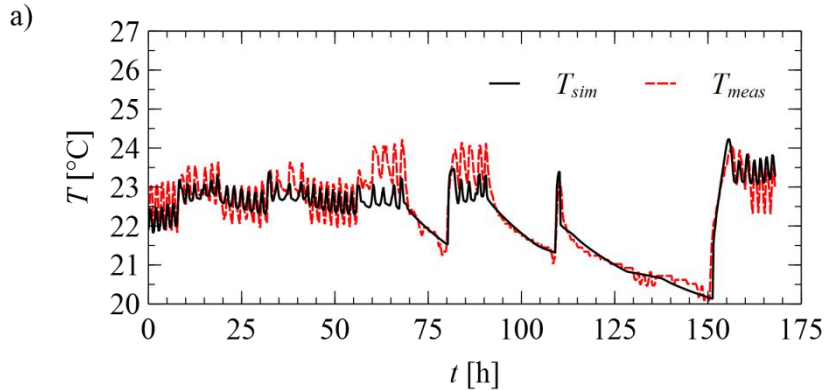
Estimated parameters:

1. average number of occupants
2. thermal resistance of external walls
3. thermal capacitance of external walls
4. thermal capacitance of internal walls
5. average interzonal airflow rate
6. CO₂ generation per person
7. solar heat gain coefficient

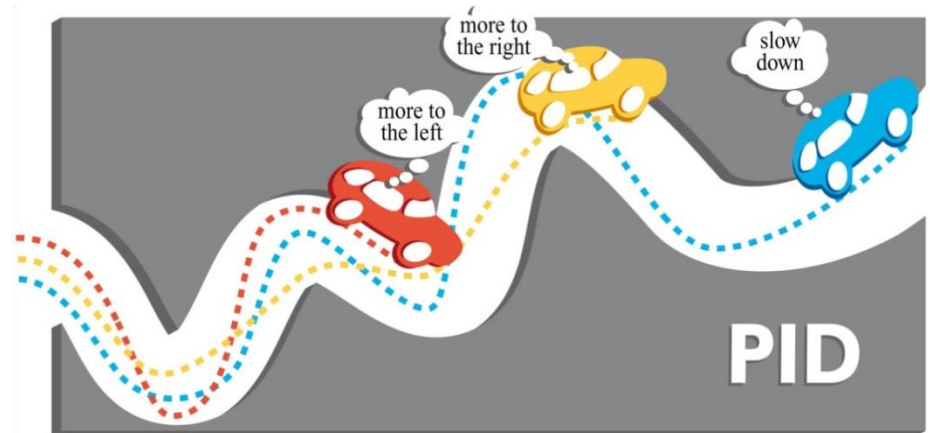
Estimation method:

Genetic Algorithm

Calibrated model results: GTH, room 1H1

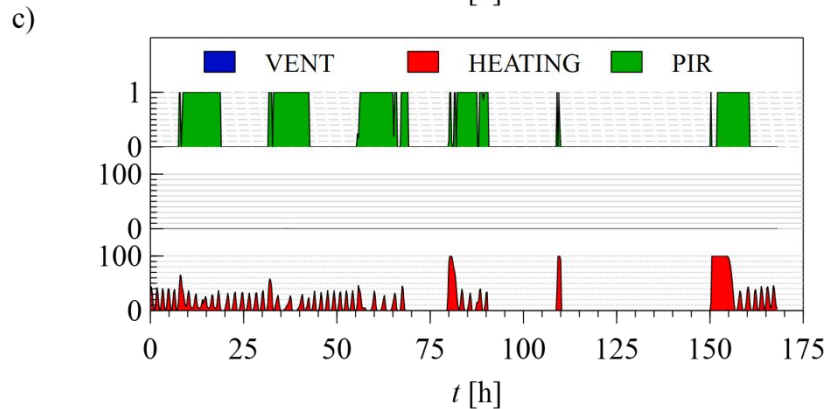
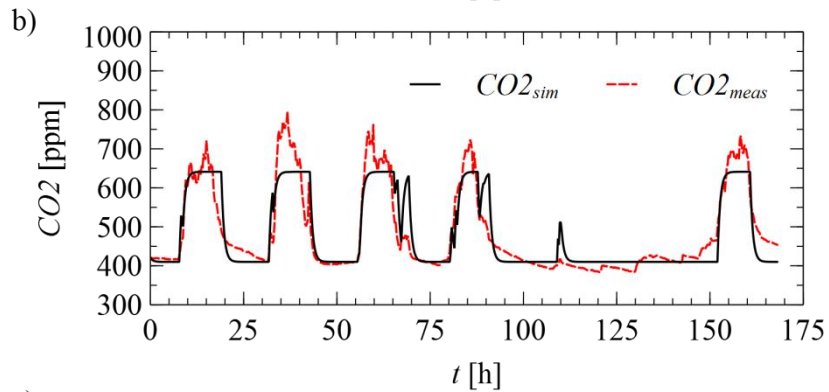
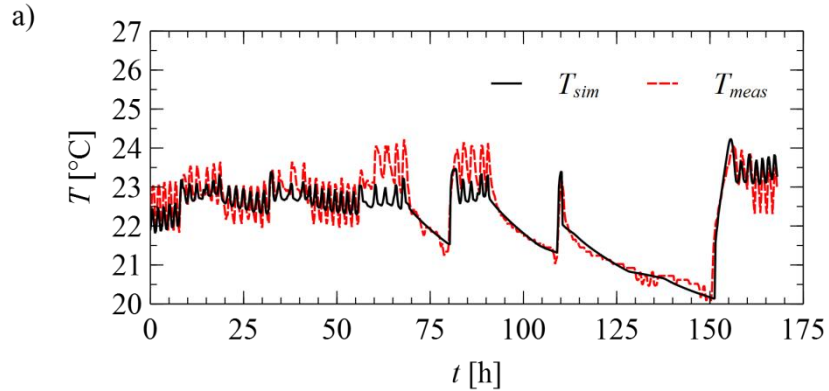


(01-03-2016 00:00:00 – 08-03-2016 00:00:00)



TOO HOT! Close valve!
TOO COLD! Open valve!

Calibrated model results: GTH, room 1H1



(01-03-2016 00:00:00 – 08-03-2016 00:00:00)

← Occupancy predictions needed to increase the accuracy of the zone model

T/CO₂ vs. camera based occupancy estimation

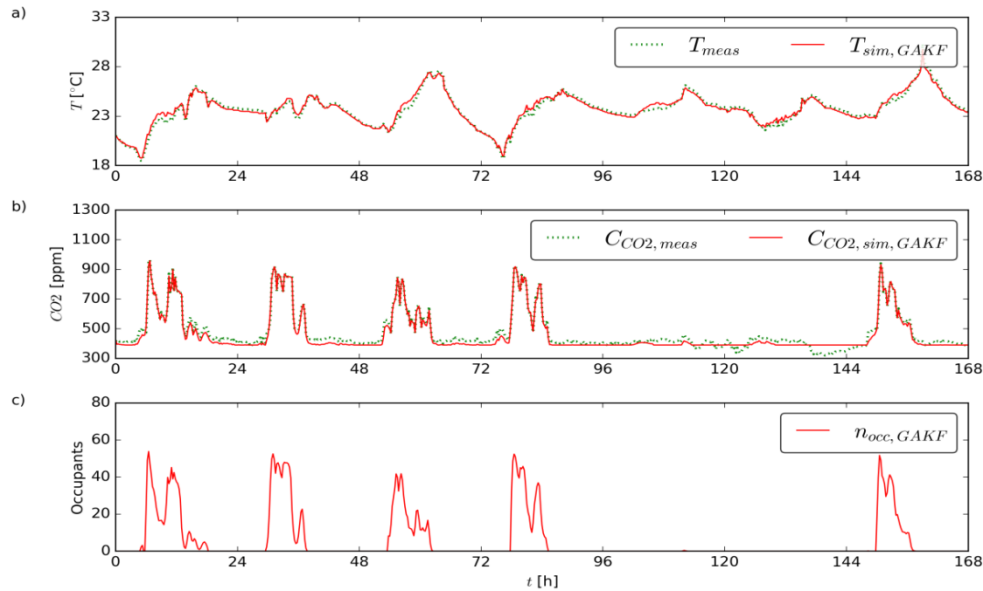


Fig. 1: a) Temperature, b) CO₂, c) Estimated number of occupants

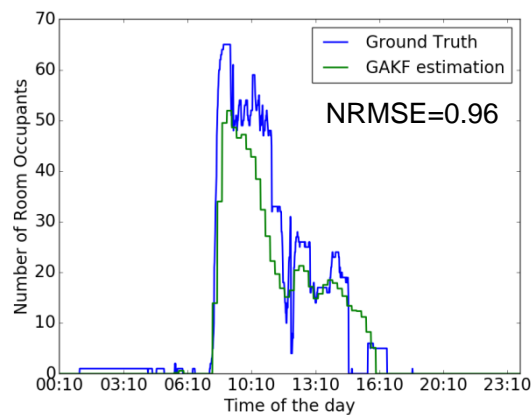


Fig. 3: T/CO₂ based estimation accuracy

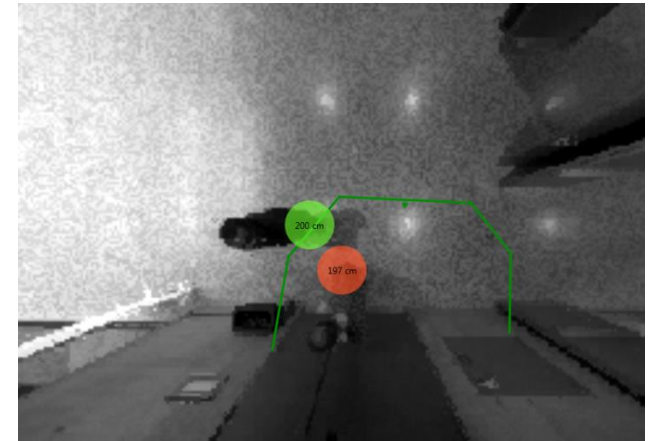


Fig. 2: Stereo vision camera view with count lines in green and detected persons shown by circles.

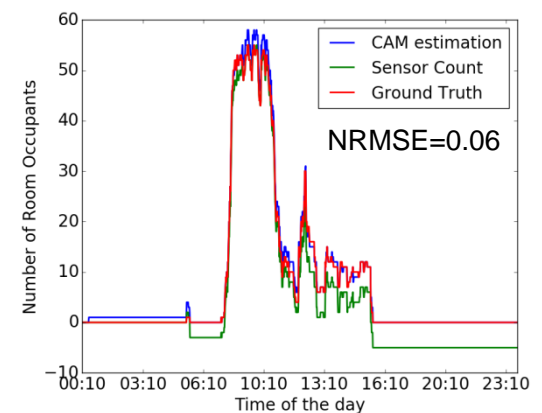


Fig. 4: Stereo vision camera based estimation accuracy

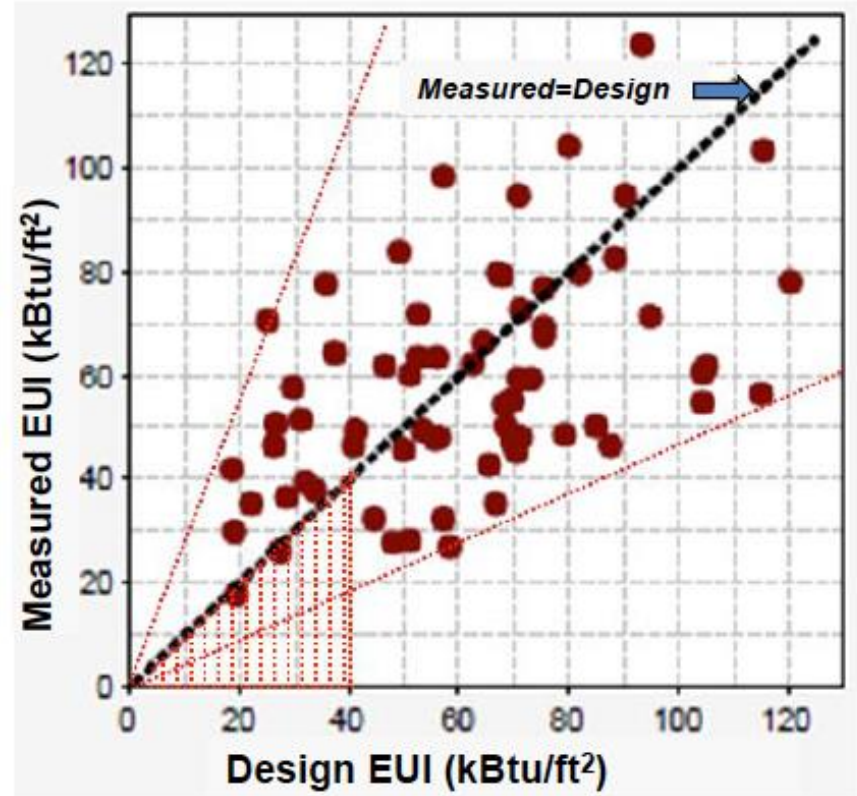
Thank you for attention!

Krzysztof Arendt
krza@mmmi.sdu.dk

<https://github.com/sdu-cfei/modest-py>

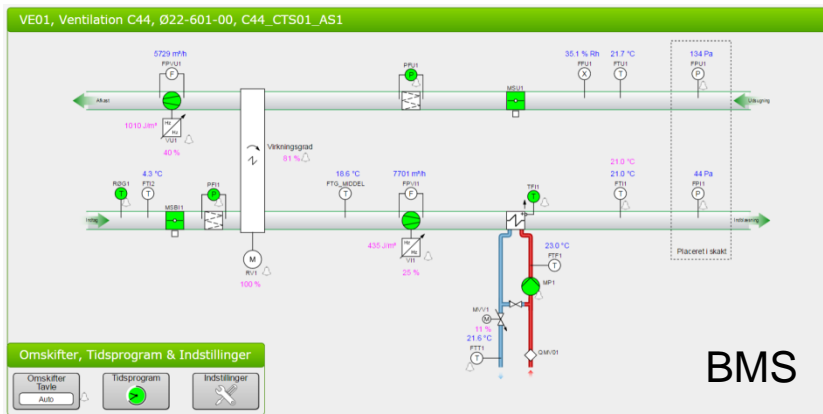
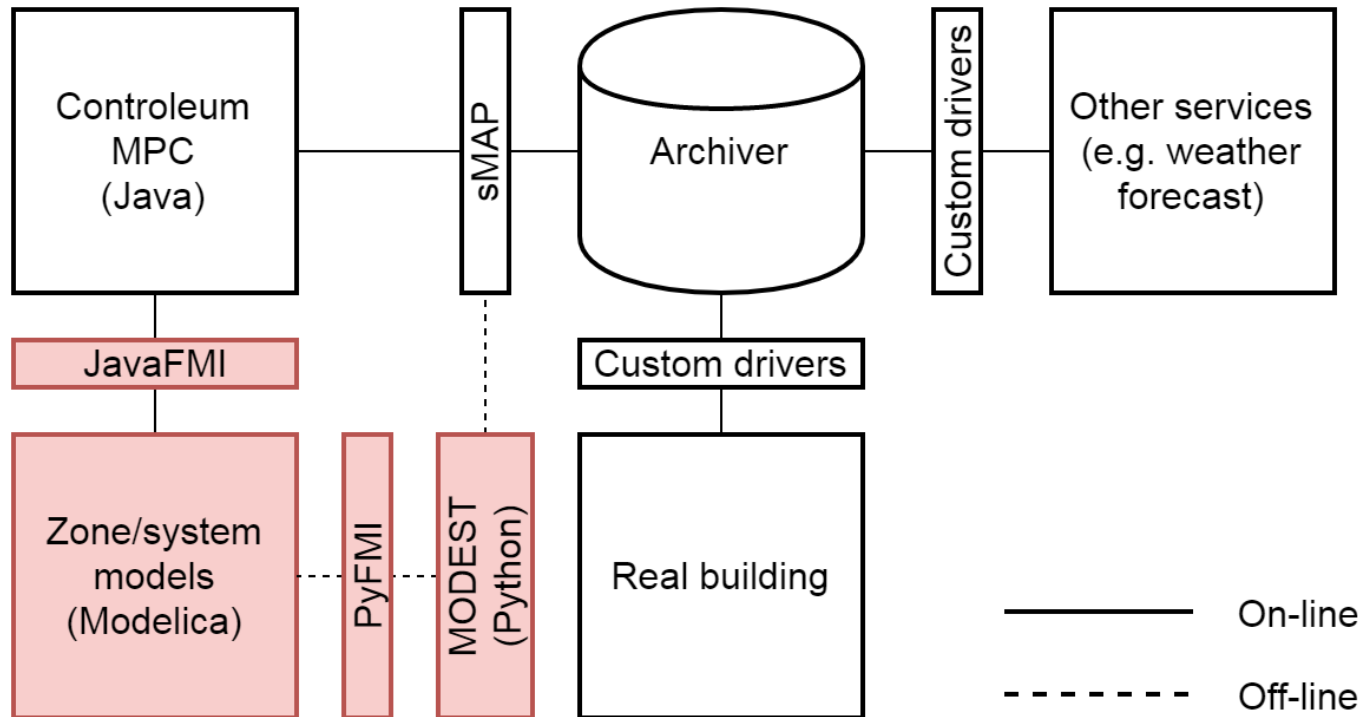
APPENDIX

Building energy challenge



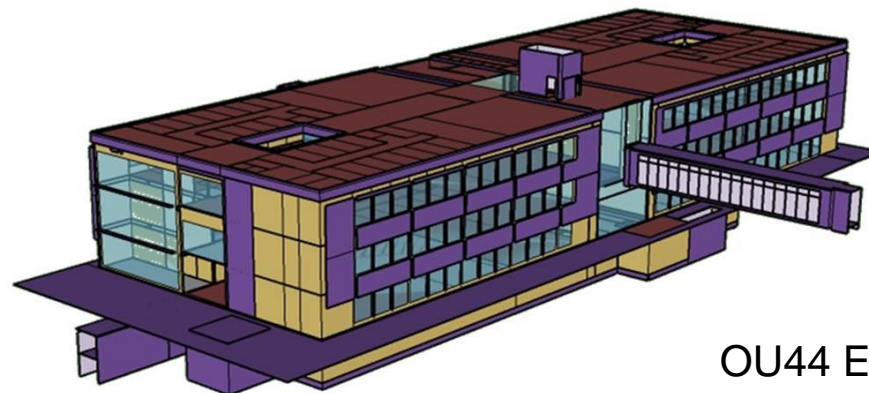
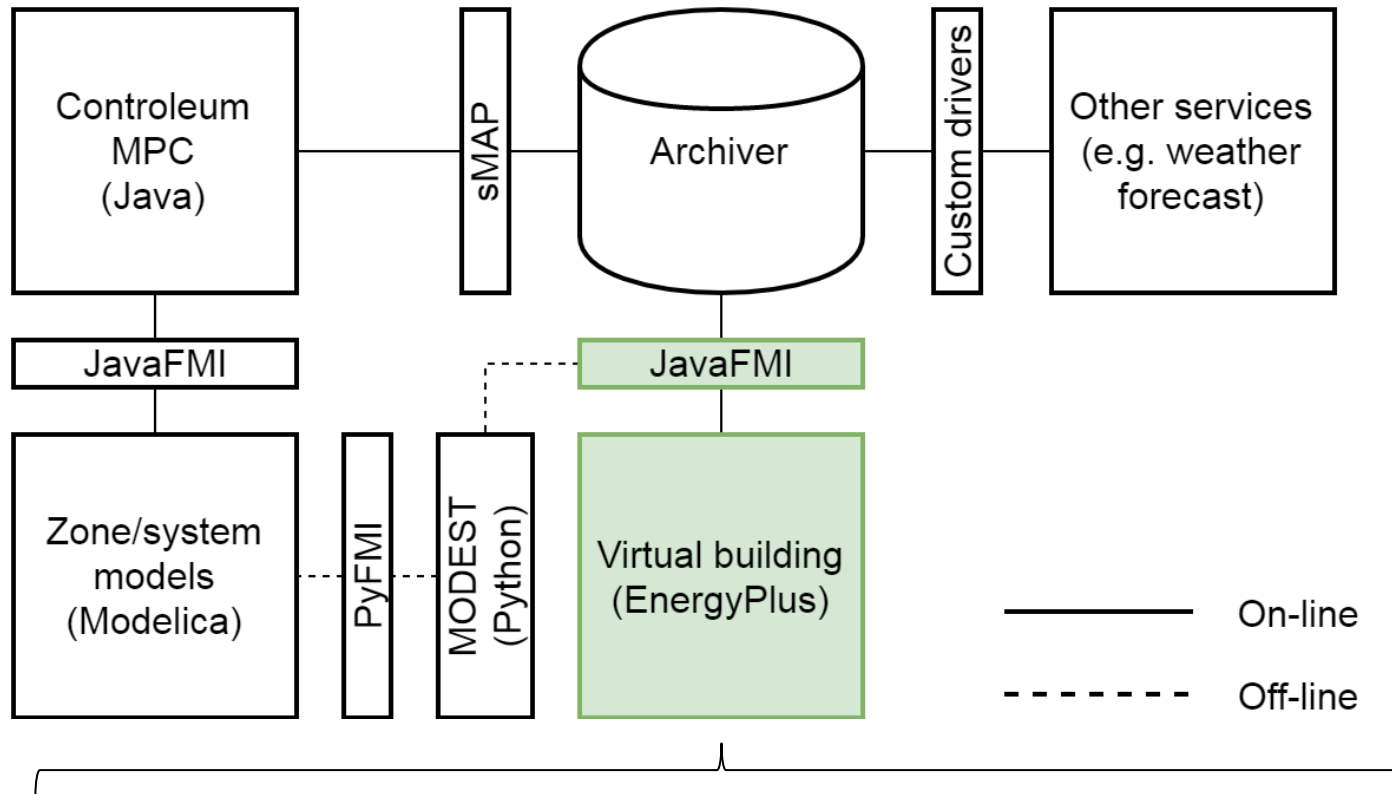
Source: Energy performance of LEED-NC buildings, NBI, 2008

SDU MPC framework



OU44
8300 m²
4 floors

SDU MPC Framework



OU44 E+ model

Non-convex example: R5C4

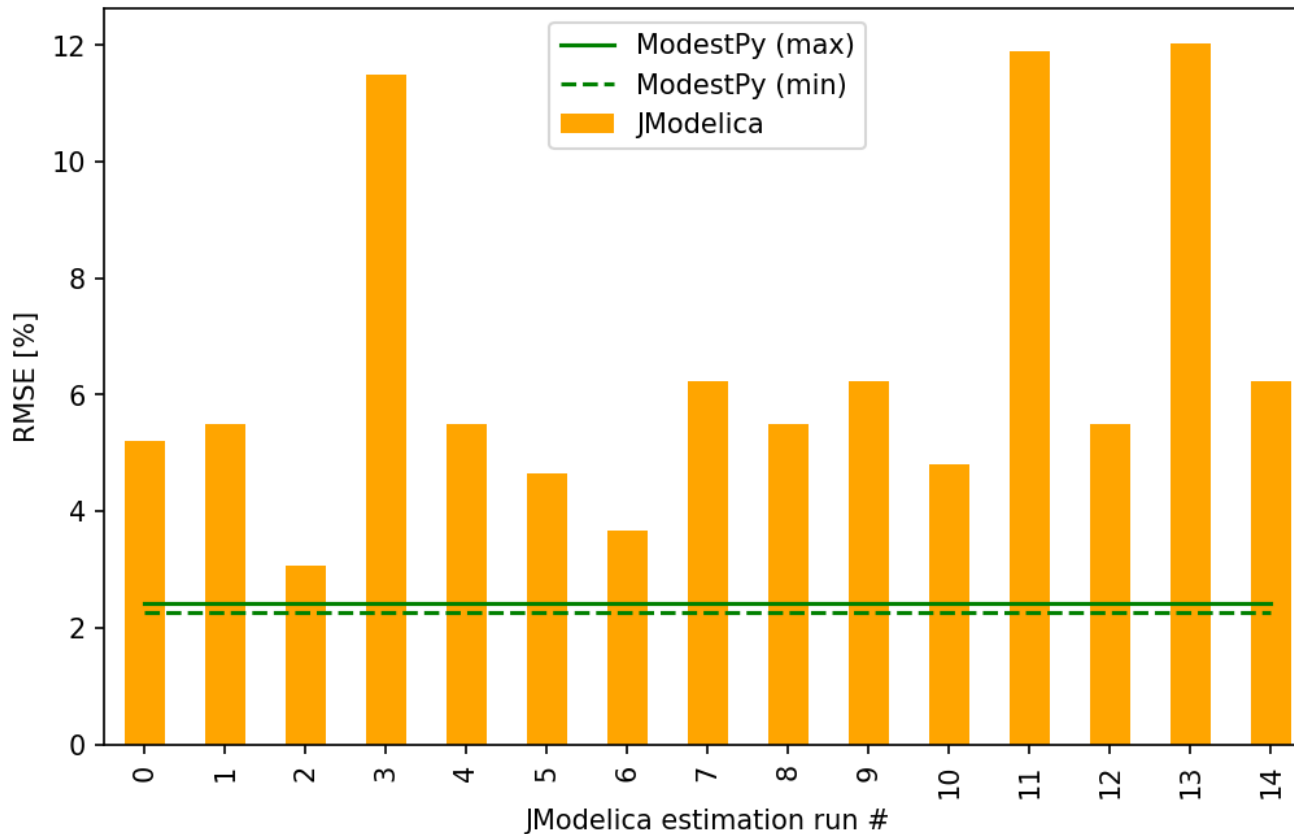


Fig: Gradient-descent (JModelica) vs. GA+HJ (ModestPy) *

- This is just an example! In many cases gradient-descent outperforms GA+HJ
- Each estimation run in JModelica used different initial guess
- Ground-truth data emulated on BESTEST 600FF

* Results produced in collaboration with **LBNL (D. Blum, L. Rivalin, M. Wetter)** using MPCPy framework: <https://github.com/lbl-srg/MPCPy>